Consistency conditions for sustained rapid turn inflation in two-field cosmological models

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## Definition

A two-dimensional oriented scalar triple is an ordered system $(\mathcal{M}, \mathcal{G}, V)$, where:

- $(\mathcal{M}, \mathcal{G})$ is a connected, oriented and borderless Riemann surface (called scalar manifold)
- $V \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ is a smooth function (called scalar potential).


## Assumptions

(1) $(\mathcal{M}, \mathcal{G})$ is complete (this ensures conservation of energy)
(2) $V>0$ on $\mathcal{M}$ (this avoids technical problems but can be relaxed)

Each scalar triple defines a model of gravity coupled to scalar fields on $\mathbb{R}^{4}$ :

$$
\mathcal{S}_{\mathcal{M}, \mathcal{G}, V}[g, \varphi]=\int_{\mathbb{R}^{4}} \mathrm{~d}^{4} x \sqrt{|g|}\left[\frac{M^{2}}{2} R(g)-\frac{1}{2} \operatorname{Tr}_{g} \varphi^{*}(\mathcal{G})-V \circ \varphi\right]
$$

Define the rescaled Planck mass $M_{0} \stackrel{\text { def. }}{=} \sqrt{\frac{2}{3}} M$, where $M$ is the reduced Planck mass. Take $g$ to describe a spatially flat FLRW universe:

$$
\mathrm{d} s_{g}^{2}:=-\mathrm{d} t^{2}+a^{2}(t) \mathrm{d} \vec{x}^{2} \quad\left(x^{0}=t \quad, \quad \vec{x}=\left(x^{1}, x^{2}, x^{3}\right) \quad, \quad a(t)>0 \forall t\right)
$$

and $\varphi$ to depend only on the cosmological time: $\varphi=\varphi(t)$.

## The cosmological equation and geometric dynamical system

Define the Hubble parameter $H(t) \stackrel{\text { def. }}{=} \frac{\partial(t)}{\partial(t)}$ and the rescaled Hubble function:

$$
\mathcal{H}: T \mathcal{M} \rightarrow \mathbb{R}_{>0}, \quad \mathcal{H}(u) \stackrel{\text { def. }}{=} \frac{1}{M_{0}} \sqrt{\|u\|^{2}+2 V(\pi(u))} \forall u \in T \mathcal{M},
$$

where $\pi: T \mathcal{M} \rightarrow \mathcal{M}$ is the bundle projection.

## Proposition

When $\mathrm{H}>0$, the equations of motion are equivalent with the cosmological equation:

$$
\nabla_{t} \dot{\varphi}(t)+\frac{1}{M_{0}} \mathcal{H}(\dot{\varphi}(t)) \dot{\varphi}(t)+\left(\operatorname{grad}_{\mathcal{G}} V\right)(\varphi(t))=0
$$

together with the Hubble condition:

$$
H(t)=\frac{1}{3 M_{0}} \mathcal{H}(\dot{\varphi}(t)) .
$$

The solutions $\varphi: I \rightarrow \mathcal{M}$ of the cosmological equation are called cosmological curves. The cosmological equation defines an autonomous dissipative geometric dynamical system on $T \mathcal{M}$.

For simplicity, we take $M=1$ i.e. $M_{0}=\sqrt{\frac{2}{3}}$.

The adiabatic and enthropic equations
Let $(T, N)$ be the positive Frenet frame of a cosmological curve $\varphi: I \rightarrow \mathcal{M}$ :

$$
T(t) \stackrel{\text { def. }}{=} \frac{\dot{\varphi}(t)}{\|\dot{\varphi}(t)\|} \quad, \quad N(t)=-J T(t)
$$

where $J \in \operatorname{End}(T \mathcal{M})$ is the complex structure determined on $\mathcal{M}$ by the conformal class of $\mathcal{G}$ :

$$
\omega(u, v)=\mathcal{G}(u, J v), \quad \text { where } \omega \stackrel{\text { def. }}{=} \operatorname{vol}_{\mathcal{G}}
$$

and let $\sigma$ be an increasing proper legth parameter for $\varphi$ :

$$
\mathrm{d} \sigma=\|\dot{\varphi}(t)\| \mathrm{d} t
$$

Projecting the cosmological equation along $T$ and $N$ gives repectively the adiabatic and ethropic equations:

$$
\ddot{\sigma}+\frac{1}{M_{0}} \mathcal{H}(\sigma, \dot{\sigma}) \dot{\sigma}+V_{T}(\sigma)=0 \quad, \quad \Omega(\sigma)=\frac{V_{N}(\sigma)}{\dot{\sigma}}
$$

where

$$
\begin{gathered}
\mathcal{H}(\sigma, \dot{\sigma})=\sqrt{\dot{\sigma}^{2}+2 V(\sigma)} \\
V_{T}(\sigma) \stackrel{\text { def. }}{=}(\mathrm{d} V)(\varphi(\sigma))(T(\sigma)), \quad V_{N}(\sigma) \stackrel{\text { def. }}{=}(\mathrm{d} V)(\varphi(\sigma))(N(\sigma))
\end{gathered}
$$

and we defined the signed turn rate of $\varphi$ through:

$$
\Omega(t) \stackrel{\text { def. }}{=}-\mathcal{G}\left(N, \nabla_{t} T\right)
$$

## Kinematic parameters

## Definition

Consider the following functions of $t$ associated to the cosmological curve $\varphi$ :

- Define the first, second and third Hubble slow roll parameters:

$$
\varepsilon=-\frac{\dot{H}}{H^{2}} \quad, \quad \eta_{\|}=-\frac{\ddot{\sigma}}{H \dot{\sigma}} \quad, \quad \xi=\frac{\dddot{\sigma}}{H^{2} \dot{\sigma}} .
$$

- The first and second turn parameters:

$$
\eta_{\perp} \stackrel{\text { def. }}{=} \frac{\Omega}{H} \quad, \quad \nu \stackrel{\text { def. }}{=} \frac{\dot{\eta_{\perp}}}{H \eta_{\perp}} .
$$

- The first IR parameter $\kappa$ and the conservative parameter $c$ :

$$
\kappa \stackrel{\text { def. }}{=} \frac{\dot{\sigma}^{2}}{2 V}, \quad c \stackrel{\text { def. }}{=} \frac{H \dot{\sigma}}{\|\mathrm{~d} V\|}
$$

## Remark

The opposite relative acceleration vector $\eta \stackrel{\text { def. }}{=}-\frac{1}{H \dot{\sigma}} \nabla_{t} \dot{\varphi}$ decomposes as $\eta=\eta_{\|} T+\eta_{\perp} N$ and we have:

$$
\varepsilon=\frac{3 \kappa}{1+\kappa}
$$

## Definition

- The first, second and third slow roll conditions are the conditions $\epsilon \ll 1$, $\left|\eta_{\|}\right| \ll 1$ and $|\xi| \ll 1$.
- The second order slow roll regime is defined by the joint conditions $\epsilon \ll 1$ and $\left|\eta_{\|}\right| \ll 1$.
- The third order slow roll regime is defined by the joint conditions $\epsilon \ll 1$, $\left|\eta_{\|}\right| \ll 1$ and $|\xi| \ll 1$.


## Definition

- The rapid turn condition is the condition $\left|\eta_{\perp}\right| \gg 1$.
- The sustained rapid turn regime is defined by the joint conditions $\left|\eta_{\perp}\right| \gg 1$ and $|\nu| \ll 1$.


## Proposition

Suppose that the second slow roll condition $\left|\eta_{\|}\right| \ll 1$ is satisfied. Then the rapid turn condition $\left|\eta_{\perp}\right| \gg 1$ is equivalent with the conservative condition $c \ll 1$.

The adapted frame
Let $\mathcal{M}_{0} \stackrel{\text { def. }}{=}\{m \in \mathcal{M} \mid(\mathrm{d} V)(m) \neq 0\}$ be the complement of the critical locus of $V$.

## Definition

The adapted frame of $(\mathcal{M}, \mathcal{G}, V)$ is the oriented orthonormal frame $(n, \tau)$ of $\mathcal{M}_{0}$ defined by the vector fields:

$$
n \stackrel{\text { def. }}{=} \frac{\operatorname{grad} V}{\|\operatorname{grad} V\|}, \tau=-J n .
$$

## Definition

The characteristic angle $\theta \in(-\pi, \pi]$ of $\varphi$ is the angle of rotation from the adapted frame $(n, \tau)$ to the Frenet frame ( $T, N$ ):

$$
T=n \cos \theta+\tau \sin \theta \quad, \quad N=-n \sin \theta+\tau \cos \theta
$$

The sign factor $s \stackrel{\text { def. }}{=} \operatorname{sign}(\sin \theta) \in\{-1,0,1\}$ is called the characteristic sign of $\varphi$.

## Proposition

We have:

$$
\eta_{\|}=3+\frac{\cos \theta}{c}, \quad \eta_{\perp}=-\frac{\sin \theta}{c} .
$$

For any vector fields $X, Y$, we use the notation:

$$
V_{X Y} \stackrel{\text { def. }}{=} \operatorname{Hess}(V)(X, Y)
$$

where $\operatorname{Hess}(V) \stackrel{\text { def. }}{=} \nabla \mathrm{d} V$ is the Riemannian Hessian of $V$.

## Definition

The nondegenerate locus of $\mathcal{M}$ is the following subset of $\mathcal{M}_{0}$ :

$$
\mathcal{U} \stackrel{\text { def. }}{=}\left\{m \in \mathcal{M}_{0} \mid \Phi_{n \tau}(m) \neq 0\right\}
$$

The scalar triple $(\mathcal{M}, \mathcal{G}, V)$ is called nondegenerate if $\mathcal{U} \neq \emptyset$.

## Theorem

Suppose that $(\mathcal{M}, \mathcal{G}, \Phi)$ is nondegenerate. Then there exist basic natural observables $\hat{\varepsilon}, \hat{\eta}_{\|}, \hat{c}, \hat{\theta}: \dot{T} \mathcal{U} \rightarrow \mathbb{R}$ associated to $\varepsilon, \eta_{\|}, c$ and $\theta$ which provide local coordinates on a small enough neighborhood of each point of $\dot{T} \mathcal{U}$.

## Proposition

We have:

$$
\begin{aligned}
& \frac{V_{T T}}{3 H^{2}}=\frac{\Omega^{2}}{3 H^{2}}+\varepsilon+\eta_{\|}-\frac{\xi}{3} \\
& \frac{V_{T N}}{H^{2}}=\frac{\Omega}{H}\left(3-\varepsilon-2 \eta_{\|}+\nu\right) .
\end{aligned}
$$

## Theorem

Suppose that the third order slow roll conditions $\varepsilon \ll 1,\left|\eta_{\|}\right| \ll 1$ and $|\xi| \ll 1$ as well as the small rate of turn condition $|\nu| \ll 1$ are satisfied. In this case, we have $\cos \theta \approx-3 c, \sin \theta \approx s \sqrt{1-9 c^{2}}$ and:

$$
\begin{aligned}
& V_{T N}^{2} \approx 3 V V_{T T} \\
& V_{T T} \approx 9 c^{2} V_{n n}-6 s c \sqrt{1-9 c^{2}} V_{n \tau}+\left(1-9 c^{2}\right) V_{\tau \tau} \\
& V_{T N} \approx-3 s c \sqrt{1-9 c^{2}}\left(V_{\tau \tau}-V_{n n}\right)-\left(1-18 c^{2}\right) V_{n \tau}
\end{aligned}
$$

These equations admit a solution $c$ with $c \ll 1$ iff:

$$
V_{n \tau}^{2} V_{\tau \tau} \approx 3 V V_{n n}^{2}
$$

up to corrections of order one in $\varepsilon, \eta_{\|}, \xi$ and $\kappa$.

## Corollary

The cosmological curve $\varphi$ satisfies the sustained rapid turn conditions with third order slow roll at cosmological time $t$ iff the following condition is satisfied at the point $m=\varphi(t)$ of $\mathcal{M}_{0}$ :

$$
V_{n \tau}^{2} V_{\tau \tau} \approx 3 V V_{n n}^{2} .
$$

In particular, such cosmological curves can be found only in regions of $\mathcal{M}_{0}$ where this condition is satisfied.

## Definition

The SRRT equation is the following condition which constrains target space metric $\mathcal{G}$ and scalar potential $V$ of the model on the noncritical submanifold $\mathcal{M}_{0}$ :

$$
V_{n \tau}^{2} V_{\tau \tau}=3 V V_{n n}^{2}
$$

The SRRT equation can be written as nonlinear differential equation for the pair $(\mathcal{G}, V)$ of $\mathcal{M}_{0}$. When $\mathcal{G}$ is fixed, it can be viewed as a nonlinear second order PDE for $V$. When $V$ is fixed, it can be viewed as a nonlinear first order PDE for the metric $\mathcal{G}$. Using isothermal coordinates, the latter can be writted as a contact Hamilton-Jacobi equation for the conformal factor of the metric $\mathcal{G}$.

Let $S \stackrel{\text { def. }}{=} \operatorname{Sym}^{2}\left(T^{*} \mathcal{M}\right)$ and $S_{+} \subset S$ be the fiber sub-bundle consisting of positive-definite tensors. When $V$ is fixed, the SRRT equation has the form:

$$
\mathcal{F}\left(j^{1}(\mathcal{G})\right)=0,
$$

where $\mathcal{F}: j^{1}(S)_{+} \rightarrow \mathbb{R}$ is a smooth function which depends on $V$.
Let $L=\operatorname{det} T^{*} \mathcal{M}=\wedge^{2} T^{*} \mathcal{M}$ be the real determinant line bundle of $\mathcal{M}$ and $L_{+}$ be its sub-bundles of positive vectors. Fixing the complex structure $J$ determined by $\mathcal{G}$, the map $\mathcal{G} \rightarrow \omega$ gives an isomorphism of fiber bundles $S_{+} \xrightarrow{\sim} L_{+}$which extends to an isomorphism $j^{1}(S)_{+} \xrightarrow{\sim} j^{1}\left(L_{+}\right)$. Use this to transport $\mathcal{F}$ to a function $H:=H_{V}^{J}: j^{1}\left(L_{+}\right) \rightarrow \mathbb{R}$. Then the SRRT equation becomes:

$$
H\left(j^{1}(\omega)\right)=0
$$

This is a contact Hamilton-Jacobi equation for $\omega \in \Gamma\left(L_{+}\right)$relative to the Cartan contact structure of $j^{1}\left(L_{+}\right)$. $H$ restricts to a cubic polynomial function on the fibers of the natural projection $j^{1}\left(L_{+}\right) \rightarrow L_{+}$.
In local isothermal coordinates $\left(x^{1}, x^{2}\right)$ on $\mathcal{M}$ relative to $J$, we have:

$$
\mathrm{d} s_{\mathcal{G}}^{2}=e^{2 \varphi}\left(\mathrm{~d} x_{1}^{2}+\mathrm{d} x_{2}^{2}\right)
$$

and one can write this contact HJ equation as a nonlinear first order PDE for the conformal factor $\varphi$, which is cubic in the partial derivatives $\partial_{1} \varphi$ and $\partial_{2} \varphi$. The equation can be solved locally through the method of characteristics, while the Cauchy boundary value problem can be approached using the theory of viscosity solutions.

