Consistency conditions for sustained rapid turn inflation in two-field cosmological models

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The SRRT equation

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Two-field cosmological models with oriented target space

Definition

A two-dimensional oriented scalar triple is an ordered system $(\mathcal{M}, \mathcal{G}, V)$, where:

- (*M*,*G*) is a connected, oriented and borderless Riemann surface (called scalar manifold)
- $V \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ is a smooth function (called scalar potential).

Assumptions

- $(\mathcal{M}, \mathcal{G})$ is complete (this ensures conservation of energy)
- **②** V > 0 on \mathcal{M} (this avoids technical problems but can be relaxed)

Each scalar triple defines a model of gravity coupled to scalar fields on \mathbb{R}^4 :

$$\mathcal{S}_{\mathcal{M},\mathcal{G},V}[g,arphi] = \int_{\mathbb{R}^4} \mathrm{d}^4 x \, \sqrt{|g|} \left[rac{M^2}{2} R(g) - rac{1}{2} \mathrm{Tr}_g arphi^*(\mathcal{G}) - V \circ arphi
ight]$$

Define the *rescaled Planck mass* $M_0 \stackrel{\text{def.}}{=} \sqrt{\frac{2}{3}}M$, where *M* is the reduced Planck mass. Take *g* to describe a spatially flat FLRW universe:

$$\mathrm{d} s^2_g := -\mathrm{d} t^2 + a^2(t) \mathrm{d} ec{x}^2 \ (x^0 = t \ , \ ec{x} = (x^1, x^2, x^3) \ , \ a(t) > 0 \ \forall t)$$

and φ to depend only on the cosmological time: $\varphi = \varphi(t)$.

The cosmological equation and geometric dynamical system

Define the Hubble parameter $H(t) \stackrel{\text{def.}}{=} \frac{\dot{a}(t)}{a(t)}$ and the rescaled Hubble function:

$$\mathcal{H}: \mathcal{TM} o \mathbb{R}_{>0} \ , \ \mathcal{H}(u) \stackrel{ ext{def.}}{=} rac{1}{M_0} \sqrt{||u||^2 + 2V(\pi(u))} \ orall u \in \mathcal{TM} \ ,$$

where $\pi: T\mathcal{M} \to \mathcal{M}$ is the bundle projection.

Proposition

When H > 0, the equations of motion are equivalent with the cosmological equation:

$$abla_t \dot{arphi}(t) + rac{1}{M_0} \mathcal{H}(\dot{arphi}(t)) \dot{arphi}(t) + (ext{grad}_\mathcal{G} V)(arphi(t)) = 0 ~,$$

together with the Hubble condition:

$$H(t)=rac{1}{3M_0}\mathcal{H}(\dot{arphi}(t))$$
 .

The solutions $\varphi: I \to \mathcal{M}$ of the cosmological equation are called cosmological curves. The cosmological equation defines an autonomous dissipative geometric dynamical system on $T\mathcal{M}$.

For simplicity, we take M = 1 i.e. $M_0 = \sqrt{\frac{2}{3}}$.

The adiabatic and enthropic equations

Let (T, N) be the positive Frenet frame of a cosmological curve $\varphi : I \to \mathcal{M}$:

$$T(t) \stackrel{\mathrm{def.}}{=} rac{\dot{arphi}(t)}{||\dot{arphi}(t)||} \ , \ \ \mathcal{N}(t) = -JT(t) \ ,$$

where $J \in \text{End}(TM)$ is the complex structure determined on M by the conformal class of \mathcal{G} :

$$\omega(u, v) = \mathcal{G}(u, Jv)$$
, where $\omega \stackrel{\text{def.}}{=} \operatorname{vol}_{\mathcal{G}}$

and let σ be an increasing proper legth parameter for φ :

$$\mathrm{d}\sigma = ||\dot{arphi}(t)||\mathrm{d}t$$
 .

Projecting the cosmological equation along T and N gives repectively the adiabatic and *ethropic* equations:

$$\ddot{\sigma} + rac{1}{M_0} \mathcal{H}(\sigma, \dot{\sigma}) \dot{\sigma} + V_T(\sigma) = 0 \ , \ \Omega(\sigma) = rac{V_N(\sigma)}{\dot{\sigma}} \ ,$$

where

$$\mathcal{H}(\sigma, \dot{\sigma}) = \sqrt{\dot{\sigma}^2 + 2V(\sigma)}$$
,

 $V_{\mathcal{T}}(\sigma) \stackrel{\text{def.}}{=} (\mathrm{d}V)(\varphi(\sigma))(\mathcal{T}(\sigma)) \ , \ V_{\mathcal{N}}(\sigma) \stackrel{\text{def.}}{=} (\mathrm{d}V)(\varphi(\sigma))(\mathcal{N}(\sigma))$

and we defined the signed turn rate of φ through:

$$\Omega(t) \stackrel{\text{def.}}{=} -\mathcal{G}(N, \nabla_t T) \quad .$$

Kinematic parameters

Definition

Consider the following functions of t associated to the cosmological curve φ :

• Define the first, second and third Hubble slow roll parameters:

$$\varepsilon = -\frac{\dot{H}}{H^2}$$
, $\eta_{\parallel} = -\frac{\ddot{\sigma}}{H\dot{\sigma}}$, $\xi = \frac{\ddot{\sigma}}{H^2\dot{\sigma}}$

• The first and second turn parameters:

$$\eta_{\perp} \stackrel{\mathrm{def.}}{=} rac{\Omega}{H} \;\;,\;\;
u \stackrel{\mathrm{def.}}{=} rac{\dot{\eta_{\perp}}}{H\eta_{\perp}}$$

• The first IR parameter κ and the conservative parameter c:

$$\kappa \stackrel{\text{def.}}{=} \frac{\dot{\sigma}^2}{2V} \ , \ \ \boldsymbol{c} \stackrel{\text{def.}}{=} \frac{H\dot{\sigma}}{||\mathrm{d}V||}$$

Remark

The opposite relative acceleration vector $\eta \stackrel{\text{def.}}{=} -\frac{1}{H\dot{\sigma}} \nabla_t \dot{\varphi}$ decomposes as $\eta = \eta_{\parallel} T + \eta_{\perp} N$ and we have:

$$\varepsilon = \frac{3\kappa}{1+\kappa}$$

Definition

- The first, second and third slow roll conditions are the conditions $\epsilon \ll 1$, $|\eta_{\parallel}| \ll 1$ and $|\xi| \ll 1$.
- The second order slow roll regime is defined by the joint conditions $\epsilon \ll 1$ and $|\eta_{||}| \ll 1.$
- The third order slow roll regime is defined by the joint conditions $\epsilon \ll 1$, $|\eta_{\parallel}| \ll 1$ and $|\xi| \ll 1$.

Definition

- The rapid turn condition is the condition $|\eta_{\perp}| \gg 1$.
- The sustained rapid turn regime is defined by the joint conditions $|\eta_{\perp}|\gg 1$ and $|\nu|\ll 1$.

Proposition

Suppose that the second slow roll condition $|\eta_{\parallel}| \ll 1$ is satisfied. Then the rapid turn condition $|\eta_{\perp}| \gg 1$ is equivalent with the conservative condition $c \ll 1$.

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The adapted frame

Let $\mathcal{M}_0 \stackrel{\text{def.}}{=} \{m \in \mathcal{M} \mid (\mathrm{d}V)(m) \neq 0\}$ be the complement of the critical locus of V.

Definition

The *adapted frame* of $(\mathcal{M}, \mathcal{G}, V)$ is the oriented orthonormal frame (n, τ) of \mathcal{M}_0 defined by the vector fields:

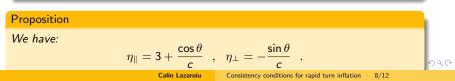
$$n \stackrel{\text{def.}}{=} \frac{\operatorname{grad} V}{||\operatorname{grad} V||}$$
, $\tau = -Jn$.

Definition

The *characteristic angle* $\theta \in (-\pi, \pi]$ of φ is the angle of rotation from the adapted frame (n, τ) to the Frenet frame (T, N):

$$T = n\cos\theta + \tau\sin\theta$$
, $N = -n\sin\theta + \tau\cos\theta$

The sign factor $s \stackrel{\text{def.}}{=} \operatorname{sign}(\sin \theta) \in \{-1, 0, 1\}$ is called the *characteristic sign* of φ .



For any vector fields X, Y, we use the notation:

$$V_{XY} \stackrel{\text{def.}}{=} \operatorname{Hess}(V)(X,Y) \ ,$$

where $\operatorname{Hess}(V) \stackrel{\text{def.}}{=} \nabla dV$ is the Riemannian Hessian of V.

Definition

The *nondegenerate locus* of \mathcal{M} is the following subset of \mathcal{M}_0 :

$$\mathcal{U}\stackrel{\mathrm{def.}}{=} \{m \in \mathcal{M}_0 \mid \Phi_{n\tau}(m) \neq 0\}$$

The scalar triple $(\mathcal{M}, \mathcal{G}, V)$ is called *nondegenerate* if $\mathcal{U} \neq \emptyset$.

Theorem

Suppose that $(\mathcal{M}, \mathcal{G}, \Phi)$ is nondegenerate. Then there exist basic natural observables $\hat{\varepsilon}, \hat{\eta}_{\parallel}, \hat{c}, \hat{\theta} : \dot{T}\mathcal{U} \to \mathbb{R}$ associated to $\varepsilon, \eta_{\parallel}, c$ and θ which provide local coordinates on a small enough neighborhood of each point of $\dot{T}\mathcal{U}$.

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Consistency conditions for sustained rapid turn with third order slow roll

Proposition

We have:

$$\frac{V_{TT}}{3H^2} = \frac{\Omega^2}{3H^2} + \varepsilon + \eta_{\parallel} - \frac{\xi}{3}$$
$$\frac{V_{TN}}{H^2} = \frac{\Omega}{H} \left(3 - \varepsilon - 2\eta_{\parallel} + \nu\right)$$

Theorem

Suppose that the third order slow roll conditions $\varepsilon \ll 1$, $|\eta_{\parallel}| \ll 1$ and $|\xi| \ll 1$ as well as the small rate of turn condition $|\nu| \ll 1$ are satisfied. In this case, we have $\cos \theta \approx -3c$, $\sin \theta \approx s\sqrt{1-9c^2}$ and:

$$\begin{split} V_{TN}^{2} &\approx 3VV_{TT} \\ V_{TT} &\approx 9c^{2}V_{nn} - 6sc\sqrt{1 - 9c^{2}}V_{n\tau} + (1 - 9c^{2})V_{\tau\tau} \\ V_{TN} &\approx -3sc\sqrt{1 - 9c^{2}}(V_{\tau\tau} - V_{nn}) - (1 - 18c^{2})V_{n\tau} \end{split}$$

These equations admit a solution c with $c \ll 1$ iff:

$$V_{n\tau}^2 V_{\tau\tau} \approx 3 V V_{nn}^2$$

up to corrections of order one in $\varepsilon, \eta_{\parallel}, \xi$ and κ .

The SRRT equation

Corollary

The cosmological curve φ satisfies the sustained rapid turn conditions with third order slow roll at cosmological time t iff the following condition is satisfied at the point $m = \varphi(t)$ of \mathcal{M}_0 :

$$V_{n\tau}^2 V_{\tau\tau} \approx 3 V V_{nn}^2$$
 .

In particular, such cosmological curves can be found only in regions of \mathcal{M}_0 where this condition is satisfied.

Definition

The *SRRT* equation is the following condition which constrains target space metric G and scalar potential V of the model on the noncritical submanifold \mathcal{M}_0 :

$$V_{n\tau}^2 V_{\tau\tau} = 3 V V_{nn}^2$$

The SRRT equation can be written as nonlinear differential equation for the pair (\mathcal{G}, V) of \mathcal{M}_0 . When \mathcal{G} is fixed, it can be viewed as a nonlinear second order PDE for V. When V is fixed, it can be viewed as a nonlinear first order PDE for the metric \mathcal{G} . Using isothermal coordinates, the latter can be writted as a *contact Hamilton-Jacobi equation* for the conformal factor of the metric \mathcal{G} .

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Let $S \stackrel{\text{def.}}{=} \operatorname{Sym}^2(T^*\mathcal{M})$ and $S_+ \subset S$ be the fiber sub-bundle consisting of positive-definite tensors. When V is fixed, the SRRT equation has the form:

 $\mathcal{F}(j^1(\mathcal{G}))=0 \ ,$

where $\mathcal{F}: j^1(S)_+ \to \mathbb{R}$ is a smooth function which depends on V. Let $L = \det T^*\mathcal{M} = \wedge^2 T^*\mathcal{M}$ be the real determinant line bundle of \mathcal{M} and L_+ be its sub-bundles of positive vectors. Fixing the complex structure J determined by \mathcal{G} , the map $\mathcal{G} \to \omega$ gives an isomorphism of fiber bundles $S_+ \xrightarrow{\sim} L_+$ which extends to an isomorphism $j^1(S)_+ \xrightarrow{\sim} j^1(L_+)$. Use this to transport \mathcal{F} to a function $H := H^J_V: j^1(L_+) \to \mathbb{R}$. Then the SRRT equation becomes:

$$H(j^1(\omega))=0$$

This is a contact Hamilton-Jacobi equation for $\omega \in \Gamma(L_+)$ relative to the Cartan contact structure of $j^1(L_+)$. *H* restricts to a cubic polynomial function on the fibers of the natural projection $j^1(L_+) \rightarrow L_+$. In local isothermal coordinates (x^1, x^2) on \mathcal{M} relative to *J*, we have:

$$\mathrm{d} \boldsymbol{s}_{\mathcal{G}}^2 = \boldsymbol{e}^{2\varphi} \big(\mathrm{d} \boldsymbol{x}_1^2 + \mathrm{d} \boldsymbol{x}_2^2 \big)$$

and one can write this contact HJ equation as a nonlinear first order PDE for the conformal factor φ , which is cubic in the partial derivatives $\partial_1 \varphi$ and $\partial_2 \varphi$. The equation can be solved locally through the method of characteristics, while the Cauchy boundary value problem can be approached using the theory of viscosity solutions.