HOMOGENEITY AND FORMALISMS OF MECHANICS

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Euler's Homogeneous Function Theorem

Let us start with an easy student exercise in the first course of Calculus, known as Euler's Homogeneous Function Theorem:

Proposition

Any C^1 -differentiable function $f : \mathbb{R}^n \to \mathbb{R}$ is homogeneous of degree 1, i.e., a function satisfying

$$f(t \cdot x) = t \cdot f(x) \quad \text{for all} \quad t > 0, \qquad (1)$$

if and only if f is linear.

It is clear that we can replace \mathbb{R}^n with any *n*-dimensional real vector space E, and the condition (1) with $\nabla_E(f) = f$, where ∇_E is the Euler vector field on E; in homogeneous coordinates,

$$\nabla_E = \sum x^i \partial_{x^i}.$$

Hence, the dual space E^* can be defined as the space of smooth 1-homogeneous functions, so the linear structure on E is determined by the multiplication by reals, $h_t(v) = tv$.

Vector bundles

Our observation can be naturally extended to vector bundles.

Traditionally, a vector bundle is defined as a locally trivial fibration $\tau: E \to M$ with an atlas of local trivializations $\tau^{-1}(U) \simeq U \times \mathbb{R}^n$ such that the transition maps are linear in fibers,

 $U \cap V \times \mathbb{R}^n \ni (x, y) \mapsto (x, A(x, y)) \in U \cap V \times \mathbb{R}^n,$

where $A(x, \cdot) \in \operatorname{GL}(n, \mathbb{R})$.

The latter property can also be expressed in terms of the multiplication by reals $h_t(x, y) = (x, ty)$:

 $A \circ h_t = h_t \circ A$ for all $t \in \mathbb{R}$.

It follows that the multiplication by reals is well-defined globally, $h_t : E \to E$, and completely determines the vector bundle structure. The projection $\tau : E \to M$ is simply h_0 .

Consequences for vector bundles

Since working with vector bundles we can reduce ourselves to the multiplication by reals $h_t(v) = t \cdot v$, one proves the following.

Corollary (Grabowski-Rotkiewicz 2009)

A smooth map Φ: E₁ → E₂ between the total spaces of two vector bundles π_i: E_i → M_i, i = 1, 2, is a morphism of vector bundles if and only if it intertwines the multiplications by reals:

 $\Phi(t \cdot v) = t \cdot \Phi(v) \,.$

In this case, the map $\varphi = \Phi_{|M_1|}$ is a smooth map between the base manifolds covered by Φ .

• Vector subbundles of a vector bundle $\tau : E \to M$ are smooth submanifolds $E_0 \subset E$ which are invariant with respect to the multiplication by reals, $h_t(E_0) \subset E_0$. In this case, E_0 is itself a vector bundle over $M_0 = \tau(E_0) = M \cap E_0$ and the multiplication by reals inherited from E.

Graded bundles

A straightforward generalization is the concept of a graded bundle $\tau: F \to M$ modelled on a graded vector space

 $\mathbb{R}^{\mathbf{d}} = \mathbb{R}^{d_1}[1] \times \cdots \times \mathbb{R}^{d_k}[k].$

We call k the degree and $\mathbf{d} = (d_1, \ldots, d_k)$ the rank of F, and view linear coordinates (y_w^a) in $\mathbb{R}^{d_w}[w]$ as being homogeneous of degree (weight) w with respect to the canonical dilation $h^{\mathbf{d}}$,

$$\begin{split} h^{\mathbf{d}}_t(y_1,\ldots,y_k) &= \left(t\cdot y_1,\ldots,t^k\cdot y_k\right), \quad y_w \in \mathbb{R}^{d_w}, \quad t \in \mathbb{R}\,, \\ \text{i.e., } y^a_w \circ h^{\mathbf{d}}_t &= t^w \cdot y^a_w. \end{split}$$

More precisely, F is a fiber bundle with the typical fiber $\mathbb{R}^{\mathbf{d}}$ and with an atlas of local trivializations $\tau^{-1}(U) \simeq U \times \mathbb{R}^{\mathbf{d}}$ such that the transition maps respect the dilation $h_t(x, y) = (x, h_t^{\mathbf{d}}(y))$,

 $U \cap V \times \mathbb{R}^n \ni (x,y) \mapsto (x,A(x,y)) \in U \cap V \times \mathbb{R}^{\mathbf{d}} \,,$

 $A \circ h_t = h_t \circ A$ for all $t \in \mathbb{R}$.

Like for vector bundles, the dilation $h_t: F \to F$ is globally defined and $\tau = h_0$.

Weight vector fields and homogeneity

Note that our graded bundles are not graded vector bundles, since the transition maps are generally not linear on the graded vector space $\mathbb{R}^{\mathbf{d}}$: for $h_t(y, z) = (ty, t^2 z)$ on \mathbb{R}^2 we have $\varphi \circ h_t = h_t \circ \varphi$, where $\varphi(y, z) = (y, z + y^2)$, but φ is not linear.

Like in the case of a vector space, we have local homogeneous coordinates (x^A, y^a_w) on F, where the coordinates x^A on M are of degree 0, and the coordinates y^a_w in fibers are of degree w. The dilation h_t is completely determined by the weight vector field $k \quad d_w$

$$\nabla_F = \sum_{w=1}^k \sum_{a=1}^{d_w} w \cdot y_w^a \partial_{y_w^a} \,.$$

We call a smooth function $f: F \to \mathbb{R}$ homogeneous of degree (weight) $\alpha \in \mathbb{R}$ if $f \circ h_t = t^{\alpha} \cdot f$ for t > 0 $(\nabla_F(f) = \alpha \cdot f)$.

A morphism of graded bundles is a smooth map respecting homogeneity degrees of functions, i.e., relating the corresponding weight vector fields \rightarrow the category GrB.

Graded bundles are polynomial

Generally, we call a tensor field K on F homogeneous of degree (weight) $\alpha \in \mathbb{R}$ if $\pounds_{\nabla_{F}} K = \alpha \cdot K.$

Proposition (Grabowski-Rotkiewicz 2012)

If $f: F \to \mathbb{R}$ is a homogeneous function of degree α , then $\alpha \in \mathbb{N}$ and f is locally a polynomial in homogeneous fiber coordinates y_w^a , with coefficients being smooth functions in the base coordinates (x^A) . Consequently, morphisms of graded bundles are polynomial in local homogeneous coordinates of degree > 0. In particular, the transition functions A(x, y) are polynomial in variables (y_w^a) , i.e., any graded bundle is a polynomial bundle.

Note that vector bundles are just graded bundles of degree 1. Another trivial example is a split graded bundle, i.e. a graded vector bundle $F = E^{1}[1] \oplus_{M} \cdots \oplus_{M} E^{k}[k],$

where E^i are vector bundles over M.

A canonical example

Example. Consider the second-order tangent bundle $\mathsf{T}^2 M$, i.e., the bundle of second jets of smooth paths $(\mathbb{R}, 0) \to M$. Writing the Taylor expansion of paths in local coordinates (x^A) on M:

$$x^{A}(t) = x^{A}(0) + \dot{x}^{A}(0)t + \ddot{x}^{A}(0)\frac{t^{2}}{2} + o(t^{2}),$$

we get local coordinates $(x^A, \dot{x}^B, \ddot{x}^C)$ on $\mathsf{T}^2 M$, which transform

$$\begin{split} & x'^A &= x'^A(x) \,, \\ & \dot{x}'^A &= \frac{\partial x'^A}{\partial x^B}(x) \, \dot{x}^B \,, \\ & \ddot{x}'^A &= \frac{\partial x'^A}{\partial x^B}(x) \, \ddot{x}^B + \frac{\partial^2 x'^A}{\partial x^B \partial x^C}(x) \, \dot{x}^B \dot{x}^C \,. \end{split}$$

Hence, associating with $(x^A, \dot{x}^B, \ddot{x}^C)$ the weights 0, 1, 2, we get a graded bundle structure of degree 2 on $\mathsf{T}^2 M$.

Due to the quadratic terms above, this is not a vector bundle! All this generalizes to higher tangent bundles $\mathsf{T}^k M$ which are canonically graded bundles of degree k.

Transition functions for graded bundles

In fact, the form of transition maps (changes of local coordinates) for a general graded bundle is quite similar,

$$\begin{aligned} x'^{A} &= x'^{A}(x), \\ y'^{a}_{w} &= y^{b}_{w} \cdot T^{a}_{b}(x) + \sum_{\substack{1 \leq n \\ w_{1} + \dots + w_{n} = w}} \frac{1}{n!} y'^{b_{1}}_{w_{1}} \cdots y'^{b_{n}}_{w_{n}} \cdot T^{a}_{b_{n} \cdots b_{1}}(x), \end{aligned}$$

where $T_b^{\ a}$ are invertible and $T_{b_n \cdots b_1}^{\ a}$ are symmetric in indices b. Note that the transition functions of coordinates of degree r involve only coordinates of degree $\leq r$, that defines a reduced graded bundle F_r of degree r (we simply 'forget' coordinates of degrees > r). Moreover, they are linear in coordinates of degree r modulo a shift by a polynomial in variables of degrees < r,

$$y_r'^a = y_r^b \cdot T_b^{\ a}(x) + \sum_{\substack{1 < n \\ w_1 + \dots + w_n = r}} \frac{1}{n!} y_{w_1}'^{b_1} \cdots y_{w_n}'^{b_n} \cdot T_{b_n \cdots b_1}^{\ a}(x) \,,$$

so the fibrations $F_r \to F_{r-1}$ are affine.

Graded bundles - the tower of affine fibrations

In this way, for any graded bundle F of degree k we get a tower of affine fibrations

$$F = F_k \xrightarrow{\tau^k} F_{k-1} \xrightarrow{\tau^{k-1}} \cdots \xrightarrow{\tau^3} F_2 \xrightarrow{\tau^2} F_1 \xrightarrow{\tau^1} F_0 = M \,.$$

Note that the bundles in the tower are only affine, so there is no canonical embedding of F_{r-1} into F_r nor F.

Example

In the case of the canonical graded bundle $F = \mathsf{T}^k M$, we get exactly the tower of natural projections of jet bundles

$$\mathsf{T}^{k}M \xrightarrow{\tau^{k}} \mathsf{T}^{k-1}M \xrightarrow{\tau^{k-1}} \cdots \xrightarrow{\tau^{3}} \mathsf{T}^{2}M \xrightarrow{\tau^{2}} \mathsf{T}M \xrightarrow{\tau^{1}} F_{0} = M.$$

For a split graded bundle we have

$$E^{1}[1] \oplus_{M} \cdots \oplus_{M} E^{k}[k] \to E^{1}[1] \oplus_{M} \cdots \oplus_{M} E^{k-1}[k-1] \to \cdots$$
$$\cdots \to E^{1}[1] \oplus_{M} E^{2}[2] \to E^{1}[1] \to M.$$

Homogeneity structures

The multiplication by reals in a vector bundle and, more generally, the dilations

 $\begin{aligned} h: \mathbb{R} \times F \to F, \quad h(t,p) = h_t(p), \end{aligned}$ which for a graded bundle $\tau: F \to M$ with local homogeneous coordinates (x^A, y^a_w) read

$$h_t(x^A, y^a_w) = (x^A, t^w y^a_w),$$

represent smooth actions of the monoid (not a group!) (\mathbb{R}, \cdot) of multiplicative reals: $h_1 = \mathrm{id}_F, \quad h_t \circ h_s = h_{ts}.$

Such actions of (\mathbb{R}, \cdot) we will call homogeneity structures.

This is because h defines the concept of homogeneity on F: $f: F \to \mathbb{R}$ is homogeneous of degree $\alpha \in \mathbb{R}$ if $f \circ h_t = t^{\alpha} \cdot f$ for t > 0. We can also use the associated weight vector field,

$$\nabla(p) = \frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t=1} h_t(p),$$

and say that a tensor field K on F is homogeneous of degree α if $\pounds_{\nabla}(K) = \alpha \cdot K$.

Graded bundle = homogeneity structure

We know that with every graded bundle there is canonically associated a homogeneity structure.

The fundamental result in the theory of graded bundles says that graded bundles and homogeneity structures are, in fact, fully equivalent concepts.

Theorem (Grabowski-Rotkiewicz 2012)

Associating canonically the homogeneity structure with a graded bundle yields an isomorphism of categories.

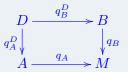
More precisely, for any homogeneity structure $h : \mathbb{R} \times F \to F$ on a manifold F, the subset $M = h_0(F)$ of F is a smooth submanifold and there is a non-negative integer $k \in \mathbb{N}$ such that $h_0 : F \to M$ is canonically a graded bundle of degree k whose homogeneity structure coincides with h. In other words, there is an atlas on F consisting of local homogeneous functions.

Double vector bundles

An important concept of a double vector bundle, introduced by Pradines in 1974, is a manifold equipped with two vector bundle structures which are compatible in a categorical sense, i.e., as a vector bundle in the category of vector bundles.

Definition

A double vector bundle (DVB in short) (D; A, B; M) is a system of four vector bundle structures and VB-morphisms,



Moreover, each of the structure maps of each of the vector bundle structures on D (the bundle projection, the zero section, the addition, and the scalar multiplication) is a morphism of vector bundles with respect to the other structure.

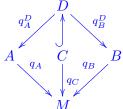
The core of a double vector bundle

Let C be the intersection of the two kernels:

 $C = \{c \in D \mid \exists \ m \in M \text{ such that } q^D_B(c) = 0^B_m, \quad q^D_A(c) = 0^A_m \}.$

It is called the core of D and, together with the map $q_C(c) = m$, it is a vector bundle $q_C : C \to M$.

We can illustrate the core in the diagram of the double vector bundle as follows.



One can prove that

$(q^D_A,q^D_B):D\to A\oplus_M B$

is an affine bundle modelled on the vector bundle $(q_A, q_B)^*(C)$.

Double vector bundles - the reference example

Let $q_A : A \to M, q_B : B \to M, q_C : C \to M$ be vector bundles. Consider the manifold

 $D = A \times_M B \times_M C \,.$

Then D is canonically a double vector bundle, with the side bundles A and B, the core C, and with the obvious projections,

 $q^D_A: A \times_M B \times_M C \to A \,, \quad q^D_B: A \times_M B \times_M C \to B \,,$

the obvious zero-sections,

$$\begin{split} \tilde{0}^A &: A \ni a_m \mapsto (a_m, 0^B_m, 0^C_m) \in D \,, \\ \tilde{0}^B &: B \ni b_m \mapsto (0^A_m, b_m, 0^C_m) \in D \,, \end{split}$$

and the obvious vector space structures in fibers.

Actually, every double vector bundle is locally of this form.

In particular, the Whitney sum $A \oplus_M B$ is a double vector bundle with the trivial core.

Double Graded Bundles

Our understanding of vector bundles as homogeneity structures extremely simplifies the 'categorical' definition of Pradines.

Theorem (Grabowski-Rotkiewicz 2009)

Two vector bundle structures, $q_A^D : D \to A$ and $q_B^D : D \to B$, on a manifold D are compatible if and only if the corresponding homogeneity structures commute:

$$h^A_t\circ h^B_s=h^B_s\circ h^A_t \ \ \, \textit{for all} \ \ \, t,s\in\mathbb{R}.$$

Definition

A double graded bundle (DGB) is a manifold D equipped with two homogeneity structures h^1, h^2 which are compatible in the sense that $h_t^1 \circ h_s^2 = h_s^2 \circ h_t^1$ for all $t, s \in \mathbb{R}$.

If degrees of h^1, h^2 are k, l, then (k, l) we call the bi-degree of D.

Of course, all this can be naturally generalized to a concept of a *n*-fold graded bundle of *n*-degree (k_1, \ldots, k_n) .

Tangent lifts of graded bundles

The compatibility condition can also be formulated as the commutation of the weight vector fields, $[\nabla^1, \nabla^2] = 0$. Note that $h_t^{\text{tot}} = h_t^1 \circ h_t^2$ defines the total graded bundle structure of D. An extension to *n*-tuple graded bundles is obvious.

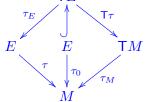
Let $\tau: F \to M$ be a graded bundle of degree k with the homogeneity structure h, which in local coordinates (x^A, y^a_w) , $1 \le w \le k$, reads $h_t(x^A, y^a_w) = (x^A, t^w y^a_w)$. Let us consider the tangent lift $(d_T h)_t = Th_t$ of h, i.e., $(d_T h)_t(x^A, y^a_w, \dot{x}^B, \dot{y}^b_w) = (x^A, t^w y^a_w, \dot{x}^B, t^w \dot{y}^b_w)$.

Proposition

The tangent lift $d_T h$ is a homogeneity structure of degree k on TF, which is compatible with the canonical vector bundle structure on TF. In other words, the tangent bundle of a graded bundle is canonically a double graded bundle.

Canonical example

 $\begin{array}{ccc} \tau: E \longrightarrow M & \tau_E: \mathsf{T}E \longrightarrow E & \mathsf{T}\tau: \mathsf{T}E \longrightarrow \mathsf{T}M \\ (x^a, y^i) \mapsto (x^a) & (x^a, y^i, \dot{x}^b, \dot{y}^j) \mapsto (x^a, y^i) & (x^a, y^i, \dot{x}^b, \dot{y}^j) \mapsto (x^a, \dot{x}^b) \\ & \mathsf{T}E \\ & \mathsf{T}E \\ & \mathsf{T}E \\ \end{array}$



 $h_t(x^a, y^i) = (x^a, ty^i), \quad (\mathbf{d}_{\mathsf{T}}h)_t(x^a, y^i, \dot{x}^b, \dot{y}^j) = (x^a, ty^i, \dot{x}^b, t\dot{y}^j)$ $\nabla = \sum_i y^i \partial_{y^i}, \quad \nabla^1 = \mathbf{d}_{\mathsf{T}}(\sum_i y^i \partial_{y^i}) = \sum_i \left(y^i \partial_{y^i} + \dot{y}^i \partial_{\dot{y}^i}\right)$ $\nabla^2 = \sum_a \dot{x}^a \partial_{\dot{x}^a} + \sum_i \dot{y}^i \partial_{\dot{y}^i}, \quad [\nabla^1, \nabla^2] = 0.$

In the case $E = \mathsf{T}M$, there is a canonical automorphism (called the flip) $\kappa : \mathsf{T}\mathsf{T}M \to \mathsf{T}\mathsf{T}M$, intertwining both VB-structures.

I INVITE YOU TO TAKE A BREAK



Phase lifts of graded bundles

To lift h_t from a graded bundle $\tau : F \to M$ of rank k to the cotangent bundle T^*F , consider the adapted coordinates (x^A, y^a_w, p_B, p^w_b) and

 $(\mathsf{T}h_{t^{-1}})^*(x^A, y^a_w, p_B, p^w_b) = (x^A, t^w y^a_w, p_B, t^{-w} p^w_b)$

for $t \neq 0$. This makes no sense for t = 0, so we define the phase lift of h by $(d_{\mathsf{T}^*}h)_t = t^k \cdot (\mathsf{T}h_{t^{-1}})^*$. This makes sense for t = 0:

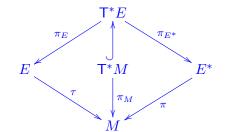
$$(\mathbf{d}_{\mathsf{T}^*}h)_t(x^A, y^a_w, p_B, p^w_b) = (x^A, t^w y^a_w, t^k p_B, t^{k-w} p^w_b).$$

Proposition

The phase lift $d_{\mathsf{T}^*}h$ is a homogeneity structure on T^*F , which is compatible with the canonical vector bundle structure. In other words, the cotangent bundle of a graded bundle is canonically a double graded bundle.

Phase lifts of vector bundles

 $\begin{aligned} \tau: E &\longrightarrow M & \pi_E: \mathsf{T}^*E &\longrightarrow E \\ (x^a, y^i) &\mapsto (x^a) & (x^a, y^i, p_b, \xi_j) \mapsto (x^a, y^i) \end{aligned}$ $h_t(x^a, y^i) &= (x^a, ty^i), \quad (\mathsf{d}_{\mathsf{T}^*}h)_t(x^a, y^i, p_b, \xi_j) = (x^a, ty^i, tp_b, \xi_j) \end{aligned}$ The Poisson bracket $\{y^i, \xi_j\}$ is δ^i_j which implies that ξ_j are coordinates dual to y^i , so $(x^a, y^i, p_b, \xi_j) \mapsto (x^a, \xi_j)$ represents a projection $\zeta: \mathsf{T}^*E \to E^*.$ We have therefore a double vector bundle



Linearity vs double vector bundles

Linearity of different geometrical structures is usually related to some DVB structures.

• A bivector field Λ on a vector bundle E is linear if the corresponding map

 $\Lambda^{\#}:\mathsf{T}^{*}E\longrightarrow\mathsf{T}E$

is a morphism of double vector bundles.

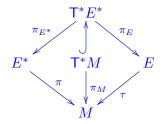
• A two-form ω on a vector bundle E is linear if the corresponding map

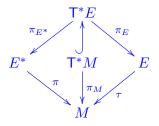
 $\omega^{\flat}:\mathsf{T} E\longrightarrow \mathsf{T}^* E$

is a morphism of double vector bundles.

- A distribution $D \subset \mathsf{T}E$ on a vector bundle E is linear if D is a double vector subbundle, i.e., D is a vector subbundle with respect to the both vector bundle structures on E.
- A (linear) connection on a vector bundle E is a horizontal distribution in TE (Ehresmann connection) which is linear.

Canonical isomorphism $T^*E \simeq T^*E^*$





Theorem (Tulczyjew 1974)

There is a canonical isomorphism of double vector bundles

 $\mathcal{R}: \mathsf{T}^* E^* \to \mathsf{T}^* E$

which in the adapted local coordinates reads

 $\mathcal{R}(x^a,\xi^i,p_b,\pi_j) = (x^a,\pi_i,-p_b,\xi^j).$

The map \mathcal{R} is simultaneously an anti-symplectomorphism.

Canonical DVBs in mechanics

Let us put now $E = \mathsf{T}M$ to be the vector bundle of kinematical configurations. We know already that $\mathsf{T}^*\mathsf{T}M$ and $\mathsf{T}^*\mathsf{T}^*M$ are canonically DVBs which are canonically isomorphic:

 $\mathcal{R}: \mathsf{T}^*\mathsf{T}^*M \to \mathsf{T}^*\mathsf{T}M,$ $(q^i, p_j, \pi_k, y^l) \mapsto (q^i, y^j, -\pi_k, p_l).$

It is easy to see that the above isomorphism is simultaneously an anti-symplectomorphism. The canonical symplectic form $\omega_M = \mathrm{d}p_i \wedge \mathrm{d}q^i$ on T^*M induces a VB-isomorphism

$$\begin{split} \beta_M : \mathsf{T}\mathsf{T}^*M \to \mathsf{T}^*\mathsf{T}^*M, \\ (q^i, p_j, \dot{q}^k, \dot{p}_l) \mapsto (q^i, p_j, -\dot{p}_k, \dot{q}^l), \end{split}$$

which is actually a DVB-isomorphism and anti-symplectomorphism with respect to the lifted symplectic structure

$$\mathrm{d}_{\mathsf{T}}(\omega_M) = \mathrm{d}\dot{p}_i \wedge \mathrm{d}q^i + \mathrm{d}p_i \wedge \mathrm{d}\dot{q}^i$$

on $\mathsf{T}\mathsf{T}^*M$.

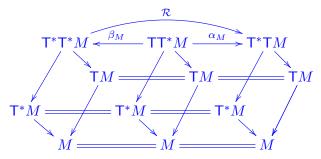
The Tulczyjew triple

Consequently,

$$\begin{split} \alpha_M &= \mathcal{R} \circ \beta_M : \mathsf{T}\mathsf{T}^*M \to \mathsf{T}^*\mathsf{T}M, \\ (q^i, p_j, \dot{q}^k, \dot{p}_l) \mapsto (q^i, \dot{q}^j, \dot{p}_k, p_l) \end{split}$$

is a DVB-isomorphism which is simultaneously a symplectomorphism. It is called the Tulczyjew isomorphism.

The full diagram of these symplectic DVB-isomorphisms, called the Tulczyjew triple, is the following:



Dynamics

The Tulczyjew's approach to formalism of mechanics uses the modern concept of first-order dynamics (first-order ODE), more general than the one based on just vector fields.

Definition

An implicit first-order dynamics on a manifold N is a submanifold $D \subset \mathsf{T}N$. A smooth curve $\gamma : \mathbb{R} \to N$ is a solution, if its tangent prolongation $\dot{\gamma} : \mathbb{R} \to \mathsf{T}N$ takes values in D.

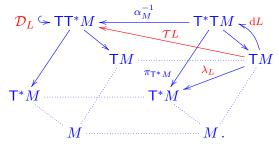
Example

A vector field X on N, defines the dynamics $D = X(N) \subset \mathsf{T}N$. Solutions for D are exactly trajectories of X. Images of vector fields are exactly those submanifolds D of $\mathsf{T}M$ which are projected diffeomorphically on M by the bundle projection $\tau_M : \mathsf{T}M \to M$.

Similarly, submanifolds of T^2N are understood as (implicit) ordinary second-order differential equations, etc.

The Tulczyjew triple - the Lagrangian side

For a Lagrangian $L : \mathsf{T}M \to \mathbb{R}$, the phase dynamics \mathcal{D}_L on T^*M is the image of the Tulczyjew differential $\mathcal{T}L = \alpha_M^{-1} \circ \mathrm{d}L$, called sometimes also the time evolution operator,



Dynamics $\mathcal{D}_L = \mathcal{T}L(\mathsf{T}M)$ is explicit for hyperregular Lagrangians only, i.e., when the Legendre map,

 $\lambda_L = \pi_{\mathsf{T}^*M} \circ \mathrm{d}L : \mathsf{T}M \to \mathsf{T}^*M, \ \lambda_L(q, \dot{q}) = \left(q, \frac{\partial L}{\partial \dot{a}}(q, \dot{q})\right),$

is a diffeomorphism. Note that the dynamics has been obtained purely geometrically and no variational calculus has been used.

The Euler-Lagrange equations

In general, the implicit dynamics looks like

$$\mathcal{D}_L = (\alpha_M^{-1} \circ \mathrm{d}L)(\mathsf{T}M) = \left\{ (q, p, \dot{q}, \dot{p}) : p = \frac{\partial L}{\partial \dot{q}}, \quad \dot{p} = \frac{\partial L}{\partial q} \right\} \,.$$

The physically meaningful phase dynamics lives on the phase space T^*M , however, one usually derives a second-order dynamics on M in the coordinate form

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial L}{\partial \dot{q}} \right) = \frac{\partial L}{\partial q}.$$

Note, however, that the information about momenta is lost in this passage. To derive the second-order equations geometrically, consider $\mathsf{TTL}:\mathsf{TTM}\to\mathsf{TTT}^*M$ and take

 $\mathcal{D}_{EL} = (\mathsf{T}\mathcal{T}L)^{-1}(\mathsf{T}^2\mathsf{T}^*M) \subset \mathsf{T}^2M,$

where we view $\mathsf{T}^2 M$ as the submanifold of holonomic vectors in $\mathsf{TT} M$, i.e., fixed points of the canonical 'flip', $\dot{q} = \delta q$.

Euler-Lagrange equations (continued)

In local coordinates,

$$\mathcal{T}L(q,\dot{q}) = \left(q, \frac{\partial L}{\partial \dot{q}}, \dot{q}, \frac{\partial L}{\partial q}(q, \dot{q})\right),$$

 \mathbf{SO}

$$\begin{aligned} \mathsf{T}\mathcal{T}L(q,\dot{q},\delta q,\delta \dot{q}) &= \left(q,\frac{\partial L}{\partial \dot{q}},\dot{q},\frac{\partial L}{\partial q},\delta q,\frac{\partial^2 L}{\partial \dot{q}^2}\delta \dot{q} + \frac{\partial^2 L}{\partial \dot{q}\partial q}\delta q, \\ \delta \dot{q},\frac{\partial^2 L}{\partial \dot{q}\partial q}\delta \dot{q} + \frac{\partial^2 L}{\partial q^2}\delta q\right). \end{aligned}$$

As holonomic vectors satisfy $\delta q = \dot{q}$ and $\delta p = \dot{p}$, we have

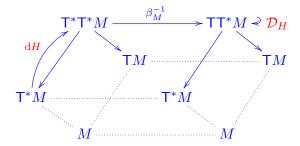
$$\mathcal{D}_{EL} = \left\{ (q, \dot{q}, \delta q, \delta \dot{q}) \, \big| \, \delta q = \dot{q}, \frac{\partial L}{\partial q} = \frac{\partial^2 L}{\partial \dot{q}^2} \delta \dot{q} + \frac{\partial^2 L}{\partial \dot{q} \, \partial q} \delta q \right\}.$$

Hence, $\mathcal{D}_{EL} \subset \mathsf{T}^2 M$ and, interpreting $\delta \dot{q}$ as \ddot{q} , we get the Euler-Lagrange equations in the form

$$\frac{\partial^2 L}{\partial \dot{q}^2} \ddot{q} + \frac{\partial^2 L}{\partial \dot{q} \partial q} \dot{q} - \frac{\partial L}{\partial q} = 0.$$

The Tulczyjew triple - the Hamiltonian side

For a Hamiltonian $H : \mathsf{T}^*M \to \mathbb{R}$, the phase dynamics \mathcal{D}_H on T^*M is always explicit – the image of the Hamiltonian vector field $X_H = \beta_M^{-1} \circ \mathrm{d}H$:



We have then:

$$\mathcal{D}_H = \beta_M^{-1} \big(\mathrm{d}H(\mathsf{T}^*M) \big) = \left\{ (q, p, \dot{q}, \dot{p}) : \dot{p} = -\frac{\partial H}{\partial q}, \quad \dot{q} = \frac{\partial H}{\partial p} \right\} \,.$$

Hence, the dynamics is described by the Hamilton equations.

Legendre transformation

The final picture is the following: Hamiltonian side phase dynamics Lagrangian side $\mathcal{D}_H \stackrel{?}{=} \mathcal{D}_L$ β_M^{-1} α_M^{-1} β_M α_M → T*TM T^*T^*M dL $\mathrm{d}H$ TM - $\mathsf{T}M$ T^*N T^*M T^*M MΜ

Note that $\mathcal{D}_H, \mathcal{D}_L, \mathrm{d}L(\mathsf{T}M), \mathrm{d}H(\mathsf{T}^*M)$ are always lagrangian submanifolds of the symplectic manifolds $\mathsf{T}\mathsf{T}^*M, \mathsf{T}^*\mathsf{T}M, \mathsf{T}\mathsf{T}^*M$, respectively.

The Legendre transformation

The Legendre transformation is a procedure of passing from a Lagrangian to a Hamiltonian description of the system. Generally, a Lagrangian description has a Hamiltonian formulation, i.e., $\mathcal{D}_L = \mathcal{D}_H$ for some Hamiltonian H, only for hyperregular Lagrangians, i.e., when the Legendre map $\lambda_L : \mathsf{T}M \to \mathsf{T}^*M$ is a diffeomorphism.

Thus, contrary to the belief of many physicists, the Lagrangian and Hamiltonian formalisms are generally not equivalent.

A way out is to consider not a single Hamiltonian but Morse families. It is well known that if the Lagrangian $L : \mathsf{T}M \to \mathbb{R}$ is hyperregular, then $\mathcal{D}_L = \mathcal{D}_H$ for the Hamiltonian function

$$H(q,p) = \dot{q}^i p_i - L$$
, where $(q,\dot{q}) = \lambda_L^{-1}(q,p)$.

In this case, the Lagrangian submanifolds $dL(\mathsf{T}M) \subset \mathsf{T}^*\mathsf{T}M$ and $dH(\mathsf{T}^*M) \subset \mathsf{T}^*\mathsf{T}^*M$ are related by $\mathcal{R} : \mathsf{T}^*\mathsf{T}^*M \to \mathsf{T}^*\mathsf{T}M$.

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THANK YOU FOR YOUR ATTENTION!



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