Hessian symmetries of multifield cosmological models

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Definition

A scalar triple is an ordered system $(\mathcal{M}, \mathcal{G}, V)$, where:

- $(\mathcal{M},\mathcal{G})$ is an oriented Riemannian *n*-manifold (the scalar manifold)
- $V \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ is a smooth function defined on \mathcal{M} (the scalar potential).

Assumptions

- $\ \, \bullet \ \, \mathcal{M} \ \, \text{is connected}.$
- 2 $(\mathcal{M},\mathcal{G})$ is complete.
- $0 \quad V > 0 \text{ on } \mathcal{M}.$

Each scalar triple defines a cosmological model with n real scalar fields:

$$\mathcal{S}_{\mathcal{M},\mathcal{G},V}[g,\varphi] = \int_{\mathbb{R}^4} \mathrm{d}^4 x \,\sqrt{|g|} \left[\frac{R(g)}{2} - \frac{1}{2} \mathrm{Tr}_g \varphi^*(\mathcal{G}) - V(\varphi) \right] \tag{1}$$

for a simply-connected and spatially flat FLRW universe:

$$\mathrm{d} s_g^2 := -\mathrm{d} t^2 + a^2(t) \mathrm{d} \vec{x}^2 \quad (x^0 = t \ , \ \vec{x} = (x^1, x^2, x^3) \ , \ a(t) > 0 \ \forall t) \quad (2)$$

in which arphi depends only on the cosmological time t:

$$\varphi = \varphi(t)$$
 . (3)

The minisuperspace Lagrangian

Substituting (2) and (3) in (1) and ignoring the integration over \vec{x} gives the minisuperspace action:

$$\mathcal{S}_{\mathcal{M},\mathcal{G},\mathbf{V}}[\mathbf{a},\varphi] = \int_{-\infty}^{\infty} \mathrm{d}t \ L_{\mathcal{M},\mathcal{G},\mathbf{V}}(\mathbf{a}(t),\varphi(t),\dot{\varphi}(t)) \ ,$$

where the minisuperspace Lagrangian is:

$$L_{\mathcal{M},\mathcal{G},V}(a,\varphi,\dot{\varphi}) \stackrel{\text{def.}}{=} -3a\dot{a}^2 + a^3 \left[\frac{1}{2}||\dot{\varphi}||_{\mathcal{G}}^2 - V(\varphi)\right] = a^3 \left[-3H^2 + \frac{1}{2}||\dot{\varphi}||_{\mathcal{G}}^2 - V(\varphi)\right]$$

Here $\dot{\varphi} \stackrel{\text{def.}}{=} \frac{d\varphi}{dt}$ and $H \stackrel{\text{def.}}{=} \frac{\dot{a}}{a}$ is the Hubble parameter. This Lagrangian describes a classical system with n + 1 degrees of freedom and configuration space $\mathcal{N} \stackrel{\text{def.}}{=} \mathbb{R}_{>0} \times \mathcal{M}$. The Euler-Lagrange equations are equivalent with:

$$3H^2 + 2\dot{H} + \frac{1}{2} ||\dot{\varphi}||_{\mathcal{G}}^2 - V(\varphi) = 0$$
$$(\nabla_t + 3H)\dot{\varphi} + (\operatorname{grad}_{\mathcal{G}} V)(\varphi) = 0$$

We must also impose the Friedmann constraint:

$$\frac{1}{2}||\dot{\varphi}||^2 + V \circ \varphi = 3H^2 \quad ,$$

which amounts to the zero energy condition.

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Proposition

When supplemented with the Friedmann constraint, the Euler-Lagrange equations of $L_{\mathcal{M},\mathcal{G},V}$ are equivalent with the cosmological equations:

$$\nabla_t \dot{\varphi} + 3H\dot{\varphi} + (\operatorname{grad}_{\mathcal{G}} V) \circ \varphi = 0$$

$$\dot{H} + 3H^2 - V \circ \varphi = 0$$

$$\dot{H} + \frac{1}{2} ||\dot{\varphi}||_{\mathcal{G}}^2 = 0$$

Remark

One can eliminate H algebraically from the cosmological equations as:

$$H(t) = \frac{1}{\sqrt{6}} \epsilon(t) \left[||\dot{\varphi}(t)||_{\mathcal{G}}^2 + 2V(\varphi(t)) \right]^{1/2} \text{, where } \epsilon(t) \stackrel{\text{def.}}{=} \operatorname{sign} H(t) \in \{-1, 0, 1\}$$

thereby reducing the latter to the n-component second order autonomous nonlinear ODE:

$$\nabla_t \dot{\varphi}(t) + \sqrt{\frac{3}{2}} \epsilon(t) \left[||\dot{\varphi}(t)||_{\mathcal{G}}^2 + 2V(\varphi(t)) \right]^{1/2} \dot{\varphi}(t) + (\operatorname{grad}_{\mathcal{G}} V)(\varphi(t)) = 0$$

which defines a (dissipative) geometric dynamical system on TM.

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Definition

A strict variational symmetry $\mathbf{X} \in \mathcal{X}(\mathbb{R} \times \mathcal{N})$ of the minisuperspace system is called strong if it is the lift of a vector field $X \in \mathcal{X}(\mathcal{N})$ defined on \mathcal{N} .

We have a natural decomposition:

$$T\mathcal{N} = T_{\perp}\mathcal{N} \oplus T_{\parallel}\mathcal{N}$$
,

where:

$$T_{\perp}\mathcal{N} \stackrel{\text{def.}}{=} p_1^*(T\mathbb{R}) \ , \ T_{\parallel}\mathcal{N} \stackrel{\text{def.}}{=} p_2^*(T\mathcal{M}) \ (p_1:T\mathcal{N} \to \mathbb{R}, \ p_2:T\mathcal{N} \to \mathcal{M}) \ .$$

Accordingly, $X \in \mathcal{X}(\mathcal{N})$ decomposes as:

$$X=X_{\perp}+X_{\parallel}$$
 .

In local coordinates (U, a, φ^i) on \mathcal{N} , we have:

$$X_{\perp}(a,\varphi) = X^{a}(a,\varphi) \frac{\partial}{\partial a} , \quad X_{\parallel} = X^{i}(a,\varphi) \frac{\partial}{\partial \varphi^{i}}$$

The Noether symmetry condition is:

$$\mathcal{L}_{\mathsf{X}^1}(L) = 0$$
 , where $\mathsf{X}^1 = j^1(\mathsf{X})$.

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Theorem

For the minisuperspace Lagrangian, the Noether symmetry condition amounts to the requirement that X_{\perp} and X_{\parallel} have the following forms:

$$X_{\perp}(a,\varphi) = rac{\Lambda(\varphi)}{\sqrt{a}} \partial_a \ , \ X_{\parallel}(a,\varphi) = Y(\varphi) - rac{4}{a^{3/2}}(\mathrm{grad}_{\mathcal{G}}\Lambda)(\varphi) \ ,$$

where $\Lambda \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ and $Y \in \mathcal{X}(\mathcal{M})$ satisfy the characteristic system of the scalar triple $(\mathcal{M}, \mathcal{G}, V)$:

$$\begin{split} &\operatorname{Hess}_{\mathcal{G}}(\Lambda) = \frac{3}{8}\mathcal{G}\Lambda \quad , \quad \mathcal{K}_{\mathcal{G}}(Y) = 0 \\ &\langle \mathrm{d}V, \mathrm{d}\Lambda \rangle_{\mathcal{G}} = \frac{3}{4}V\Lambda \quad , \quad Y(V) = 0 \quad . \end{split}$$

which can also be written in the index-full form:

$$\begin{pmatrix} \partial_i \partial_j - \Gamma^k_{ij} \partial_k \end{pmatrix} \Lambda = \frac{3}{8} \mathcal{G}_{ij} \Lambda , \quad \nabla_i Y_j + \nabla_j Y_i = 0$$

$$\mathcal{G}^{ij} \partial_i V \partial_j \Lambda = \frac{3}{4} V \Lambda , \quad Y^i \partial_i V = 0 .$$

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Visible and Hessian symmetries

The characteristic system naturally separates into the Λ -system:

$$\begin{aligned} \operatorname{Hess}_{\mathcal{G}}(\Lambda) &= \frac{3}{8}\mathcal{G}\Lambda\\ \langle \mathrm{d}\,V, \mathrm{d}\Lambda\rangle_{\mathcal{G}} &= \frac{3}{4}\,V\Lambda\end{aligned}$$

and the Y-system:

 $\mathcal{K}_{\mathcal{G}}(Y) = 0$ Y(V) = 0.

Definition

A non-trivial solution $\Lambda \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ of the Λ -system is called a Hessian symmetry of $(\mathcal{M}, \mathcal{G}, V)$. A scalar triple which admits Hessian symmetries is called a Hessian triple.

Definition

A non-trivial solution $Y \in \mathcal{X}(\mathcal{M})$ of the Y-system is called a visible symmetry of $(\mathcal{M}, \mathcal{G}, V)$. A triple which admits visible symmetries is called a visibly symmetric triple.

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Visible and Hessian symmetries

Let $N(\mathcal{M}, \mathcal{G}, V)$ denote the vector space of solutions of the characteristic system and $N_H(\mathcal{M}, \mathcal{G}, V)$, $N_V(\mathcal{M}, \mathcal{G}, V)$ denote the vector spaces of solutions of the Λ - and Y-systems.

Proposition

There exists a linear isomorphism:

 $N(\mathcal{M},\mathcal{G},V)\simeq_{\mathbb{R}} N_{H}(\mathcal{M},\mathcal{G},V)\oplus N_{V}(\mathcal{M},\mathcal{G},V)$.

In particular, a scalar triple $(\mathcal{M}, \mathcal{G}, V)$ admits strong Noether symmetries iff it is Hessian or visibly symmetric (or both).

A generic scalar triple $(\mathcal{M}, \mathcal{G}, V)$ does not admit any strong Noether symmetries. Since existence of visible symmetries is a classical problem, we focus on characterizing Hessian symmetries and Hessian scalar triples.

Remark

Existence of a Hessian Noether symmetry simplifies various cosmological problems, for example allows one to give a useful exact formula for the total number of e-folds during inflation, which is valid without 'slow roll' or 'slow turn' assumptions.

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Reconstruction of V from the gradient flow of Λ

One can solve second equation in the Λ -system through the method of characteristics. Let γ be a gradient flow curve of Λ with gradient flow parameter q:

$$rac{\mathrm{d}\gamma(q)}{\mathrm{d}q} = -(\mathrm{grad}_\mathcal{G} \Lambda)(\gamma(q)) \quad .$$

The second equation of the Λ -system (4) implies:

$$rac{\mathrm{d}}{\mathrm{d}q}V(\gamma(q)) = -\langle \mathrm{d}V,\mathrm{d}\Lambda
angle \Big|_{\gamma(q)} = -rac{3}{4}V(\gamma(q)) \ ,$$

which gives:

$$V(\gamma(q)) = V(\gamma(q_0))e^{-rac{3}{4}\int_{q_0}^{q} \wedge \mathrm{d}q}$$

This determines V along the stable and unstable manifolds (with respect to Λ) of any critical point c of Λ . If p_+ lies in the stable manifold $\mathcal{M}^{\Lambda}_+(c)$ of c, then there exists a gradient flow line $\gamma : [0, +\infty) \to \mathcal{M}$ of Λ such that $\gamma(0) = p_+$ and $\gamma(+\infty) = c$. If p_- lies in the unstable manifold $\mathcal{M}^{\Lambda}_-(c)$ of c, then there exists a gradient flow line $\gamma : (-\infty, 0] \to \mathcal{M}$ of Λ such that $\gamma(0) = p_-$ and $\gamma(-\infty) = c$. In these cases, we have:

$$V(p_{\pm}) = V(c)e^{\pm \frac{3}{4}\int_{\gamma} \Lambda \mathrm{d}q}$$

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Definition

The Hessian endomorphism $\widehat{\operatorname{Hess}}_{\mathcal{G}}(\Lambda) \in \operatorname{End}_{\mathcal{G}}^{s}(T\mathcal{M})$ of $(\mathcal{M},\mathcal{G})$ is defined by:

 $\operatorname{Hess}_{\mathcal{G}}(\Lambda)(X,Y)=\mathcal{G}(X,\widehat{\operatorname{Hess}}_{\mathcal{G}}(\Lambda)(Y)) \ , \ \forall X,Y\in \mathcal{X}(\mathcal{TM}) \ .$

The (\mathbb{R} -linear) Hesse operator $\widehat{\operatorname{Hess}}_{\mathcal{G}} : \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R}) \to \operatorname{End}_{\mathcal{G}}^{s}(\mathcal{TM})$ of $(\mathcal{M}, \mathcal{G})$ associates to $\Lambda \in \mathcal{C}^{\infty}(\mathcal{TM}, \mathbb{R})$ its Hessian endomorphism $\widehat{\operatorname{Hess}}_{\mathcal{G}}(\Lambda)$.

In local coordinates (U, x^1, \ldots, x^n) on \mathcal{M} , we have:

$$\widehat{\operatorname{Hess}}_{\mathcal{G}}(\Lambda)|_{\mathcal{U}} = \widehat{\operatorname{Hess}}_{\mathcal{G}}(\Lambda)_{i}^{\ j} \operatorname{dx}^{i} \otimes \partial_{j} \ , \ \mathrm{where} \ \ \widehat{\operatorname{Hess}}_{\mathcal{G}}(\Lambda)_{i}^{\ j} = \mathcal{G}^{jk} \left[\partial_{i} \partial_{k} - \Gamma_{ik}^{\prime} \partial_{l} \right] \Lambda \ .$$

Definition

A Hesse function of $(\mathcal{M}, \mathcal{G})$ with parameter $\beta > 0$ is a smooth function $\Lambda \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ which satisfies the Hesse equation with parameter β :

$$\operatorname{Hess}_{\mathcal{G}}(\Lambda) = \beta^2 \Lambda \, \mathcal{G} \Longleftrightarrow \widehat{\operatorname{Hess}}_{\mathcal{G}}(\Lambda) = \beta^2 \Lambda \operatorname{id}_{\mathcal{TM}} \, .$$

A unit Hesse function of $(\mathcal{M}, \mathcal{G})$ is a Hesse function Λ of $(\mathcal{M}, \mathcal{G})$ for $\beta = 1$.

Remark. In our application to cosmological models we have $\beta = \sqrt{3/8}$.

The Hesse index and Hesse manifolds

Definition

Let $S_{\beta}(\mathcal{M}, \mathcal{G})$ be the vector space of solutions of the Hesse equation with parameter β . The Hesse index of $(\mathcal{M}, \mathcal{G})$ is $\operatorname{ind}(\mathcal{M}, \mathcal{G}) \stackrel{\text{def.}}{=} \dim S_1(\mathcal{M}, \mathcal{G})$. A Hesse manifold is a Riemannian manifold $(\mathcal{M}, \mathcal{G})$ for which $\operatorname{ind}(\mathcal{M}, \mathcal{G}) > 0$.

Proposition

We have $S_{\beta}(\mathcal{M},\mathcal{G}) = S_1(\mathcal{M},\beta^2\mathcal{G}).$

Proposition

The following statements hold for any $\Lambda \in S_{\beta}(\mathcal{M}, \mathcal{G}) \setminus \{0\}$:

• The set
$$Z(\Lambda) \stackrel{\text{def.}}{=} \{ p \in \mathcal{M} | \Lambda(p) = (d\Lambda)(p) = 0 \}$$
 is empty.

2 The \mathbb{R} -linear map $e_p : S_\beta(\mathcal{M}, \mathcal{G}) \to \mathbb{R} \oplus T_p\mathcal{M}$ defined through:

$$e_p(\Lambda) \stackrel{ ext{def.}}{=} eta \Lambda(p) + (ext{grad}_\mathcal{G} \Lambda)(p) \in \mathbb{R} \oplus \mathcal{T}_p \mathcal{M} \hspace{0.2cm}, \hspace{0.2cm} orall \Lambda \in \mathcal{S}_eta(\mathcal{M},\mathcal{G})$$

is injective for every $p \in \mathcal{M}$. Thus $\operatorname{ind}(\mathcal{M}, \mathcal{G}) \leq 1 + \dim \mathcal{M}$.

Definition

We say that $(\mathcal{M}, \mathcal{G})$ is maximally Hesse if $\operatorname{ind}(\mathcal{M}, \mathcal{G}) = 1 + \dim \mathcal{M}$.

Local radial expansion and the sectional curvature condition

Let $r_{\mathcal{G}}(p) = \operatorname{injrad}_{p}(\mathcal{M}, \mathcal{G}), (r, \theta) \in (0, r_{\mathcal{G}}(p)) \times [0, \pi]^{n-2} \times (\mathbb{R}/2\pi)$ be normal spherical coordinates at $p, \nu(\theta) \in S^{n-1}, u(r, \theta) = r\nu(\theta) \in B^{n}(r_{\mathcal{G}}(p))$ and $q(r, \theta) \stackrel{\text{def.}}{=} \exp_{p}(u(r, \theta)) \in U_{p} \stackrel{\text{def.}}{=} \exp_{p}(u(B^{n}(r_{\mathcal{G}}(p))).$

Proposition (Local radial expansion of Hesse functions)

Let $\Lambda \in \mathcal{C}^{\infty}(U_p, \mathbb{R})$ be a Hesse function of $(U_p, \mathcal{G}|_{U_p})$. Then:

$$\Lambda(q(r,\theta)) = \Lambda(p) \cosh(\beta r) + \frac{1}{\beta} (\partial_r \Lambda)(p) \sinh(\beta r)$$

Moreover, Λ is identically zero or is a Morse function.

Proposition (Sectional curvature condition on Hesse manifolds)

Let $\Lambda \in S_{\beta}(\mathcal{M}, \mathcal{G}) \setminus \{0\}$. Then the following open set is non-empty:

$$U(\Lambda) \stackrel{\text{def.}}{=} \{ p \in \mathcal{M} | (\mathrm{d}\Lambda)(p) \neq 0 \} = \{ p \in \mathcal{M} | (\mathrm{grad}_{\mathcal{G}}\Lambda)(p) \neq 0 \}$$

For any $p \in U(\Lambda)$ and any 2-plane $\pi \subset T_p \mathcal{M}$ containing $(\operatorname{grad}_G \Lambda)(p)$, we have $K_p(\pi) = -\beta^2$, where $K_p(\pi)$ denotes the sectional curvature.

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Definition

The β -Hesse pairing of two smooth functions $f_1, f_2 \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ is the smooth function $\mathcal{B}_{\beta}(f_1, f_2) \in \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ defined through:

$$\mathcal{B}_{\beta}(f_1,f_2) \stackrel{\text{def.}}{=} \beta^2 f_1 f_2 - \langle \operatorname{grad}_{\mathcal{G}} f_1, \operatorname{grad}_{\mathcal{G}} f_2 \rangle_{\mathcal{G}} \ .$$

Proposition

Let $\Lambda_1, \Lambda_2 \in S_\beta(\mathcal{M}, \mathcal{G})$. Then $\mathcal{B}_\beta(\Lambda_1, \Lambda_2)$ is constant on \mathcal{M} .

Hence restriction to $S_{\beta}(\mathcal{M},\mathcal{G})$ gives a real-valued bilinear pairing:

$$(\ ,\)_{\beta}:\mathcal{S}_{\beta}(\mathcal{M},\mathcal{G})\times\mathcal{S}_{\beta}(\mathcal{M},\mathcal{G})\rightarrow\mathbb{R}\ ,\ (\Lambda_{1},\Lambda_{2})_{\beta}\stackrel{\mathrm{def.}}{=}\mathcal{B}_{\beta}(\Lambda_{1},\Lambda_{2})\ .$$

For $p \in \mathcal{M}$, let $(,)_p : (\mathbb{R} \oplus T_p \mathcal{M}) \times (\mathbb{R} \oplus T_p \mathcal{M}) \to \mathbb{R}$ be the Minkowski pairing:

$$(\tau_1 + v_1, \tau_2 + v_2)_p \stackrel{\text{def.}}{=} \tau_1 \tau_2 - \mathcal{G}_p(v_1, v_2) \ , \ \forall \tau_1, \tau_2 \in \mathbb{R} \ , \ \forall v_1, v_2 \in \mathcal{T}_p \mathcal{M} \ .$$

Proposition

For any $\Lambda \in S_1(\mathcal{M}, \mathcal{G})$ and $p \in \mathcal{M}$, the map $e_p : (S_1(\mathcal{M}, \mathcal{G}), (,)_1) \to (\mathbb{R} \oplus T_p\mathcal{M}, (,)_p)$ is an injective isometry.

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The Hesse representation

The isometry group $\operatorname{Iso}(\mathcal{M},\mathcal{G})$ acts naturally on $\mathcal{C}^{\infty}(\mathcal{M},\mathbb{R})$:

$$\varphi^*(f) \stackrel{\text{def.}}{=} f \circ \varphi^{-1} , \ \forall \varphi \in \operatorname{Iso}(\mathcal{M}, \mathcal{G}) \ \forall f \in \mathcal{C}^\infty(\mathcal{M}, \mathbb{R}) \ .$$

This action preserves the subspace $S_{\beta}(\mathcal{M}, \mathcal{G}) \subset \mathcal{C}^{\infty}(\mathcal{M}, \mathbb{R})$ and restricts to a linear representation $\mathcal{R}_{\mathcal{G}} : \operatorname{Iso}(\mathcal{M}, \mathcal{G}) \to \operatorname{Aut}_{\mathbb{R}}(S_{\beta}(\mathcal{M}, \mathcal{G}))$ of the isometry group, called the Hesse representation:

$$\mathcal{R}_\mathcal{G}(arphi) \stackrel{ ext{def.}}{=} arphi^*(\Lambda) = \Lambda \circ arphi^{-1} \ , \ \ orall \Lambda \in \mathcal{S}_eta(\mathcal{M},\mathcal{G})$$

Proposition

The Hesse representation is $(,)_{\beta}$ -orthogonal, i.e. any representation operator $R_{\mathcal{G}}(\varphi) \ (\varphi \in \operatorname{Iso}(\mathcal{M}, \mathcal{G}))$ preserves the Hesse pairing.

Definition

A Hesse function $\Lambda \in S_{\beta}(\mathcal{M}, \mathcal{G})$ is called:

- time-like, if $(\Lambda, \Lambda)_{\mathcal{S}} > 0$
- space-like, if $(\Lambda, \Lambda)_{\mathcal{S}} < 0$
- light-like, if $(\Lambda, \Lambda)_{\mathcal{S}} = 0$.

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The hyperbolic ball

Let
$$D^n \stackrel{\text{def.}}{=} \{ u \in \mathbb{R}^n \mid 0 \leq ||u||_{\mathcal{E}} < 1 \}$$
 $(||u||_{\mathcal{E}} \stackrel{\text{def.}}{=} \sqrt{u_1^2 + \ldots + u_n^2}).$

Definition

The hyperbolic ball is the complete Riemannian manifold:

$$\mathbb{D}^n \stackrel{\text{def.}}{=} (\mathbb{D}^n, \mathcal{G}_n)$$
,

where G_n be the Poincaré ball metric, i.e. the unique complete metric on D^n of constant sectional curvature $K_{G_n} = -1$.

We have:

$$\mathrm{d} s^2_{G_n} = \frac{4}{(1-||u||^2_E)^2} \sum_{i=1}^n \mathrm{d} u^2_i = \frac{4}{(1-\rho^2)^2} (\mathrm{d} \rho^2 + \rho^2 \mathrm{d} \theta^2) \ ,$$

where (ρ, θ) are spherical coordinates in \mathbb{R}^n , with $\theta = (\theta_1, \dots, \theta_{n-1})$ and:

$$\mathrm{d}\theta^2 = \sum_{i=1}^{n-1} h_i^2(\theta) \mathrm{d}\theta_i^2$$

is the squared line element on S^{n-1} , with Lamé coefficients $h_1(\theta) = 1$ and:

$$h_i(heta) = \prod_{j \le i-1} \sin(heta_j) \ , \ \forall i = 2, \dots, n$$
 .

The hyperboloid model and the Weierstrass map

Consider the (n+1)-dimensional Minkowski space $\mathbb{R}^{1,n} \stackrel{\text{def.}}{=} (\mathbb{R}^{n+1}, (,))$, where:

$$(x,y) \stackrel{\text{def.}}{=} x_0 y_0 - \sum_{i=1}^n x_i y_i = \eta^{\mu\nu} x_\mu x_\nu$$
.

Define $\vec{x} \stackrel{\text{def.}}{=} (x^1, \dots, x^n)$, so that $x = (x^0, \vec{x})$ and $(x, y) = x^0 y^0 - \vec{x} \cdot \vec{y}$, where \cdot denotes the Euclidean scalar product in \mathbb{R}^n . Let S_n^+ denote the future sheet of the hyperboloid (x, x) = 1:

$$S_n^+ \stackrel{\text{def.}}{=} \{x \in \mathbb{R}^{n+1} | (x,x) = 1 \& x_0 > 0\} = \left\{x \in \mathbb{R}^{n+1} | x_0 = \sqrt{1 + x_1^2 + \ldots + x_n^2}\right\}$$

For any $x \in S_n^+$, define $u_i \stackrel{\text{def.}}{=} \frac{x_i}{x_0+1}$. Then S_n^+ is diffeomorphic with D^n through the Weierstrass map $\Xi : D^n \to S_n^+$, which is given by:

$$\Xi(u) \stackrel{\text{def.}}{=} \left(\frac{1 + ||u||_{E}^{2}}{1 - ||u||_{E}^{2}}, \frac{2u_{1}}{1 - ||u||_{E}^{2}}, \dots, \frac{2u_{n}}{1 - ||u||_{E}^{2}} \right)$$

The components $\Xi^{\nu}(u)$ satisfy the relation $\eta_{\mu\nu}\Xi^{\mu}(u)\Xi^{\nu}(u) = -1$ and are Weierstrass coordinates of $u \in \mathbb{D}^n$. Moreover, Ξ is an isometry from \mathbb{D}^n to S_n^+ , when S_n^+ is endowed with the Riemannian metric induced by the opposite of the Minkowski metric (,).

Theorem

The hyperbolic ball \mathbb{D}^n is a maximally Hesse manifold. Moreover, the family $\mathcal{E} \stackrel{\text{def.}}{=} (\Xi^{\mu})_{\mu=0,\dots,n}$ is an orthonormal basis of $(\mathcal{S}_1(\mathbb{D}^n), (,)_1)$:

$$(\Xi^{\mu}, \Xi^{\nu})_{1} = \eta^{\mu\nu}$$
, $\forall \mu, \nu = 0, \dots, n$.

In particular, we have $(\mathcal{S}_1(\mathbb{D}^n), (,)_1) \simeq \mathbb{R}^{1,n}$.

Hence a Hesse function on \mathbb{D}^n has the general form:

$$\Lambda_B = (B, \Xi) = B_\mu \Xi^\mu = \eta_{\mu\nu} B^\mu \Xi^\nu \quad (B \in \mathbb{R}^{n+1}) \quad .$$

The map $\Lambda: \mathbb{R}^{n+1} \to \mathcal{S}_1(\mathbb{D}^n)$ given by $\Lambda(B) \stackrel{\text{def.}}{=} \Lambda_B$ is a linear isomorphism.

Proposition

The Hesse pairing of \mathbb{D}^n is given by:

$$(\Lambda_{B_1},\Lambda_{B_2})_{\mathcal{S}}=(B_1,B_2) \hspace{0.2cm}, \hspace{0.2cm} \forall B_1,B_2\in \mathbb{R}^{n+1}$$

Thus $\Lambda : \mathbb{R}^{1,n} = (\mathbb{R}^{n+1}, (,)) \rightarrow (\mathcal{S}_1(\mathbb{D}^n), (,)_1)$ is an isometry.

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 $\operatorname{Iso}^+(\mathbb{D}^n) = \operatorname{Iso}_o(\mathbb{D}^n) \simeq \operatorname{SO}^+(1, n) = \operatorname{O}_o(1, n)$ acts on \mathbb{R}^{n+1} (and hence on the hyperboloid model S_n^+) through the fundamental representation:

$$\mathbb{R}^{n+1}
i x \to U x \in \mathbb{R}^{n+1}$$
, $\forall U \in \mathrm{SO}^+(1, n)$.

The natural action $u \to \varphi_U(u)$ of $\operatorname{Iso}^+(\mathbb{D}^n)$ on \mathbb{D}^n is uniquely determined by:

$$\Xi(\varphi_U(u)) = U\Xi(u) , \quad \forall U \in \mathrm{SO}^+(1,n)$$
.

Proposition

The Hesse representation of $Iso^+(\mathbb{D}^n) = SO^+(1, n)$ is equivalent with the fundamental representation of $SO^+(1, n)$ through the map Λ :

 $\mathcal{R}(U)(\Lambda_B) = \Lambda_{U(B)}$, $\forall B \in \mathbb{R}^{n+1}$, $\forall U \in \mathrm{SO}^+(1, n)$.

Proposition

Two time-like Hesse functions Λ_B, Λ_{B'} ∈ S₁(Dⁿ) lie on the same orbit iff (B, B) = (B', B')(> 0) and sign(B⁰) = sign(B'⁰). The set of time-like orbits of Iso₊(D) on S₁(Dⁿ) is in bijection with {-1,1} × R_{>0}. The time-like orbit corresponding to (ε, K) ∈ {-1,1} × R_{>0} is diffeomorphic with the sheet sign(B⁰) = ε of the two-sheeted hyperboloid (B, B) = K.
Two space-like Hesse functions Λ_B, Λ_{B'} ∈ S₁(Dⁿ) lie on the same orbit iff (B, B) = (B', B')(< 0). The set of space-like orbits of Iso₊(M, G) on S₁(Dⁿ) is in bijection with R_{<0}. The space-like orbit corresponding to K ∈ R_{<0} is diffeomorphic with the one-sheeted hyperboloid (B, B) = K.
There exist exactly two non-trivial light-like orbits of Iso⁺(Dⁿ) on S₁(Dⁿ), which coincide with the connected components of the complement of the origin in the light cone.

Up to conjugation \sim in SO⁺(1, n), we have:

$$\operatorname{Stab}_{\operatorname{Iso}^{+}(\mathbb{D}^{n})}(\Lambda_{B}) \sim \begin{cases} \operatorname{SO}(n) & \text{if } (B,B) > 0 \text{ (time-like)} \\ \operatorname{SO}^{+}(1,n-1) & \text{if } (B,B) < 0 \text{ (space-like)} \\ \operatorname{ISO}_{o}(n-1) & \text{if } (B,B) = 0 \text{ (light-like)} \end{cases}$$

where $ISO_o(n-1)$ is the special Euclidean group in n-1 dimensions.

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Any hyperbolic *n*-manifold is a Riemannian quotient $(\mathcal{M}, G) = \mathbb{D}^n/\Gamma$ of the Poincaré ball \mathbb{D}^n by a discrete subgroup $\Gamma \subset \operatorname{Iso}^+(\mathbb{D}^n) \simeq \operatorname{SO}^+(1, n)$. Let $\pi : \mathbb{D}^n \to \mathcal{M}$ be the canonical projection. When $n \ge 3$, Mostow's rigidity theorem implies that (\mathcal{M}, G) is determined by $\pi_1(\mathcal{M}) \simeq \Gamma$ up to isometry; when n = 2, the hyperbolic metric G can have moduli. Let $\mathcal{S}_1(\mathbb{D}^n)^{\Gamma}$ be the space of Γ -invariant Hesse functions on \mathbb{D}^n .

Theorem

The map $\pi^* : \mathcal{C}^{\infty}(\mathcal{M}) \to \mathcal{C}^{\infty}(D^n)^{\Gamma}$ defined through:

$$\pi^*(\Lambda) \stackrel{\text{def.}}{=} \Lambda \circ \pi$$

induces a linear isomorphism from $S_1(\mathcal{M}, G)$ to $S_1(\mathbb{D}^n)^{\Gamma}$. In particular, (\mathcal{M}, G) is a Hesse manifold iff Γ conjugates in $SO^+(1, n)$ to a discrete subgroup of $SO^+(1, n)$, $ISO_o(n-1)$ or SO(n).

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The hyperbolic disk

Consider the open disk of unit Euclidean radius in the complex u-plane:

$$\mathrm{D}^2 \stackrel{\mathrm{def.}}{=} \{ u \in \mathbb{C} \mid 0 \leq |u| < 1 \}$$
 .

The Poincaré disk metric is:

$$\mathrm{d}s_{G_2}^2 = \frac{4}{(1-|u|^2)^2} |\mathrm{d}u|^2 = \frac{4}{(1-\rho^2)^2} (\mathrm{d}\rho^2 + \rho^2 \mathrm{d}\theta^2) \ ,$$

where $\rho \stackrel{\text{def.}}{=} |u|$ and $\theta \stackrel{\text{def.}}{=} \arg(u) \in [0, 2\pi)$ are polar coordinates on the *u*-plane. We have:

$$\mathrm{Iso}^+(\mathbb{D}^2)\simeq\mathrm{PSL}(2,\mathbb{R})\simeq\mathrm{PSU}(1,1)\stackrel{\mathrm{def.}}{=}\mathrm{SU}(1,1)/\{-l_2,l_2\}$$
 ,

where ${\rm SU}(1,1)\simeq {\rm SL}(2,\mathbb{R})$ is the closed subgroup of ${\rm SL}(2,\mathbb{C})$ defined through:

$$\begin{split} &\mathrm{SU}(1,1) \stackrel{\mathrm{def.}}{=} \{ U \in \mathrm{Mat}(2,\mathbb{C}) | U^{\dagger} = J U^{-1} J \& \det U = +1 \} \\ &\mathrm{The \ matrix} \ J \stackrel{\mathrm{def.}}{=} \left[\begin{array}{c} 1 & 0 \\ 0 & -1 \end{array} \right] \text{ satisfies } J^{\dagger} = J = J^{-1}. \text{ We have:} \\ &\mathrm{SU}(1,1) = \{ U(\eta,\sigma) \Big| \eta, \sigma \in \mathbb{C} : |\eta|^2 - |\sigma|^2 = 1 \} \\ &\mathrm{subset}, \\ \mathrm{where} \ U(\eta,\sigma) \stackrel{\mathrm{def.}}{=} \left[\begin{array}{c} \eta & \sigma \\ \overline{\sigma} & \overline{\eta} \end{array} \right] \text{ and } \mathrm{SU}(1,1) \text{ acts on } \mathrm{D}^2 \text{ through:} \\ &\varphi_U(u) = \frac{\eta u + \sigma}{\overline{\sigma} u + \overline{\eta}} \quad (u \in \mathrm{D}) \end{array} \end{split}$$

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Hesse functions on the hyperbolic disk

Consider the future sheet of the hyperboloid (x, x) = 1 in $\mathbb{R}^{1,2} = (\mathbb{R}^3, (,))$:

$$S_2^+ \stackrel{\mathrm{def.}}{=} \{x \in \mathbb{R}^3 | (x,x) = 1 \ \& \ x_0 > 0\} = \{x \in \mathbb{R}^3 | x_0 = \sqrt{1 + x_1^2 + x_2^2}\} \ .$$

The Weierstrass map $\Xi: \mathrm{D}^2 \to S_2^+$ is given by:

$$\equiv (u) \stackrel{\text{def.}}{=} \left(\frac{1+|u|^2}{1-|u|^2}, \frac{2\text{Re}u}{1-|u|^2}, \frac{2\text{Im}u}{1-|u|^2} \right)$$

The components $\Xi^{\mu}(u)$ are the Weierstrass coordinates of $u \in D^2$.

Proposition

 $\mathcal{E} \stackrel{\text{def.}}{=} (\Xi^0, \Xi^1, \Xi^2)$ is an orthonormal basis of the 3-dimensional Minkowski space $(\mathcal{S}_1(\mathbb{D}^2), (,)_1)$:

$$(\Xi^{\mu},\Xi^{\nu})_{1}=\eta^{\mu\nu}$$
 , $\forall\mu,\nu=0,1,2$.

Hence the general Hesse function on D^2 has the form:

$$\Lambda_B(u) = (B, \Xi(u)) = B_\mu \Xi^\mu(u) = B^0 \frac{1+|u|^2}{1-|u|^2} - 2B^1 \frac{\operatorname{Re} u}{1-|u|^2} - 2B^2 \frac{\operatorname{Im} u}{1-|u|^2}$$

with arbitrary $B = (B^0, B^1, B^2) \in \mathbb{R}^3$. The unit Hesse pairing is given by:

$$(\Lambda_B,\Lambda_{B'})_1=(B,B')=\eta_{\mu\nu}B^{\mu}B'^{
u}$$
 .

Proposition

The Hesse representation of $Iso^+(D^2) = PSU(1,1)$ is induced by the adjoint representation of SU(1,1).

We have:

$$\Xi(\varphi_U(u)) = \mathrm{Ad}_0(U)(\Xi(u)) \;, \; \; \forall u \in \mathrm{D} \;, \; \; \forall U \in \mathrm{SU}(1,1)$$

where the Hesse representation $\operatorname{Ad}_0: \operatorname{SU}(1,1) \to \operatorname{Aut}_{\mathbb{R}}(\mathbb{R}^3)$ is given by:

$$\operatorname{Ad}_{0}(U) = \begin{bmatrix} |\eta|^{2} + |\sigma|^{2} & -2\operatorname{Re}(\eta\bar{\sigma}) & 2\operatorname{Im}(\eta\bar{\sigma}) \\ -2\operatorname{Re}(\eta\sigma) & \operatorname{Re}(\eta^{2} + \sigma^{2}) & -\operatorname{Im}(\eta^{2} - \sigma^{2}) \\ -2\operatorname{Im}(\eta\sigma) & \operatorname{Im}(\eta^{2} + \sigma^{2}) & \operatorname{Re}(\eta^{2} - \sigma^{2}) \end{bmatrix}$$

The Killing pairing on the Lie algebra $\mathrm{su}(1,1) \simeq \mathbb{R}^3$ identifies with the Minkowski pairing (,) through an isomorphism which identifies Ad_0 with the adjoint representation of $\mathrm{SU}(1,1)$. Ad_0 preserves this pairing and descends to an isomorphism of groups $\overline{\mathrm{Ad}}_0 : \mathrm{PSU}(1,1) \xrightarrow{\sim} \mathrm{SO}_o(1,2)$.

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Orbit classification of solutions

Proposition

- Two time-like Hesse functions $\Lambda_B, \Lambda_{B'}$ belong to the same (time-like) orbit of PSU(1,1) iff (B,B) = (B',B')(>0) and $sign(B^0) = sign(B'^0)$. The set of time-like orbits is in bijection with $\{-1,1\} \times \mathbb{R}_{>0}$. The time-like orbit corresponding to $(\epsilon, K) \in \{-1,1\} \times \mathbb{R}_{>0}$ is diffeomorphic with the sheet $sign(B^0) = \epsilon$ of the two-sheeted hyperboloid (B,B) = K.
- **2** Two space-like Hesse functions $\Lambda_B, \Lambda_{B'}$ belong to the same orbit of PSU(1,1) iff (B,B) = (B',B')(<0). The set of space-like orbits is in bijection with $\mathbb{R}_{<0}$. The space-like orbit corresponding to $K \in \mathbb{R}_{<0}$ is diffeomorphic with the one-sheeted hyperboloid (B,B) = K.
- The non-trivial light-like orbits of PSU(1,1) on $S_1(\mathbb{D}^2)$ coincide with the connected components of the complement of the origin in the light cone.

The stabilizer subgroup of a nontrivial solution Λ_B in $\mathrm{PSU}(1,1)\simeq\mathrm{SO}_{o}(1,2)$ is:

$$\operatorname{Stab}_{\operatorname{PSU}(1,1)}(\Lambda_B) \simeq \begin{cases} \operatorname{SO}(2) & \text{if } (B,B) > 0 \text{ (time-like)} \\ \operatorname{SO}_o(1,1) \simeq (\mathbb{R},+) & \text{if } (B,B) < 0 \text{ (space-like)} \\ \operatorname{ISO}_o(1) \simeq (\mathbb{R},+) & \text{if } (B,B) = 0 \text{ (light-like)} \end{cases}$$

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Proposition

Let Γ be a non-trivial discrete subgroup of $\mathrm{PSU}(1,1)$. Suppose that there exists a non-trivial unit Hesse function $\Lambda \in \mathcal{S}_1(\mathbb{D}^2)$ such that

- $\Gamma \subset \operatorname{Stab}_{\operatorname{PSU}(1,1)}(\Lambda).$ Then Γ is a cyclic group. Moreover:
- If ∧ is time-like then Γ is a finite cyclic group and hence is generated by an elliptic element of PSU(1,1).
- If ∧ is light-like then Γ is an infinite cyclic group generated by a parabolic element of PSU(1,1)
- If Λ is space-like then Γ is an infinite cyclic group generated by a hyperbolic element of PSU(1, 1).

Corollary

Let Γ be a non-trivial surface group (i.e. a non-trivial Fuchsian group without elliptic elements) which stabilizes a non-trivial unit Hesse function $\Lambda \in S_1(\mathbb{D}^2)$. Then Λ is light-like or space-like and Γ is an infinite cyclic group. Moreover:

- If ∧ is light-like then Γ is a parabolic cyclic group and D²/Γ is a hyperbolic cusp.
- If ∧ is space-like then Γ is a hyperbolic cyclic group and D²/Γ is a hyperbolic annulus.

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Proposition

Any complete Hesse surface (Σ, G) is hyperbolic.

Theorem

A hyperbolic surface $(\Sigma, G) \simeq \mathbb{D}^2/\Gamma$ with $\Gamma \neq 1$ is Hesse iff Γ is a parabolic or a hyperbolic cyclic group, in which case we have $\operatorname{ind}(\Sigma, G) = 1$. Moreover:

- If Γ is a parabolic cyclic group (i.e. if (Σ, G) is a hyperbolic cusp), then $S_1(\mathbb{D}^2)^{\Gamma} \simeq S_1(\Sigma, G)$ is a light ray of $(S_1(\mathbb{D}^2), (,)_S) \simeq \mathbb{R}^{1,2}$.
- If Γ is a hyperbolic cyclic group (i.e. if (Σ, G) is a hyperbolic annulus), then $S_1(\mathbb{D}^2)^{\Gamma} \simeq S_1(\Sigma, G)$ is a space-like ray of $(S_1(\mathbb{D}^2), (,)_S) \simeq \mathbb{R}^{1,2}$.

Corollary

The two-field cosmological model defined by a complete surface (Σ, \mathcal{G}) uniformized by $\Gamma \subset \mathrm{PSU}(1,1)$ admits Hessian Noether symmetries iff (Σ, \mathcal{G}) is an elementary surface of Gaussian curvature $K_{\mathcal{G}} = -3/8$. In this case, the space of Hesse functions is three-dimensional when $\Gamma \simeq 1$ (hyperbolic disk) and one-dimensional when $\Gamma \simeq \mathbb{Z}$ (hyperbolic cusp or annulus).

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